

# TESTABLE HIGH-PERFORMANCE LARGE-SCALE DISTRIBUTED ERLANG

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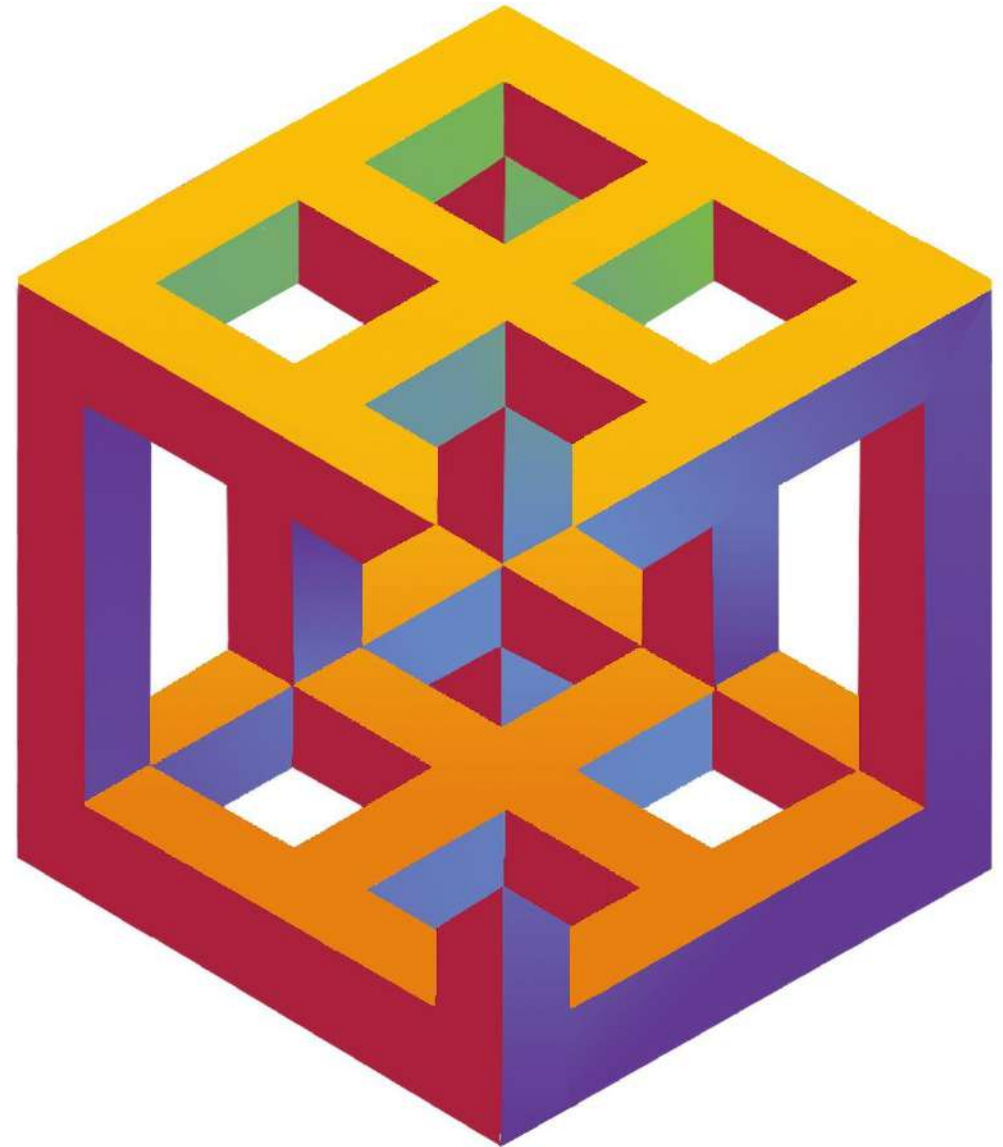
Heather C. Miller

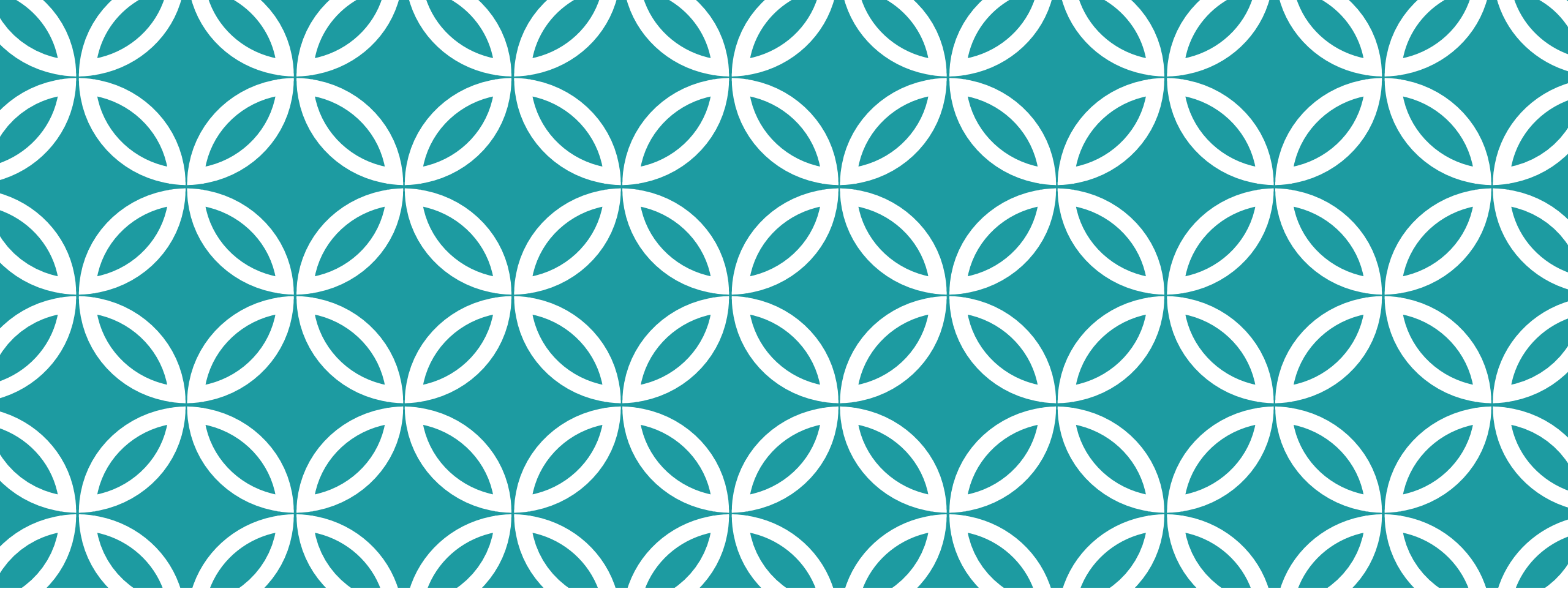
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 institute for  
SOFTWARE  
RESEARCH





# MOTIVATION

What are actors used for and what are the problems with actors?

# MOTIVATION

Distributed systems programming is still **very hard**:

- How to manage state?
- How do we manage concurrency?

Modern actor systems are still limited in terms of both scalability and latency!

- Encapsulation for state
- Pervasive concurrency – thousands of actors working together
- Asynchronous messaging – no shared memory between actors

Demonstrated success:

- Erlang: Call of Duty, League of Legends, WhatsApp
- Orleans: Halo, Gears of War

# ACTOR EXAMPLE: DISTRIBUTED ERLANG

```
call(Dst, Msg, Timeout) ->  
  Dst ! Msg,
```

```
  receive
```

```
    Response ->  
      Response
```

```
  after
```

```
    Timeout ->  
      {error, timeout}
```

```
  end
```

```
end.
```

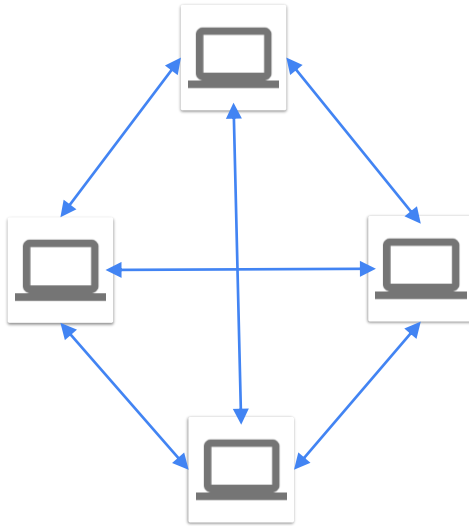
```
Pid = spawn(fun() -> call(OtherPid, Message, 1000) end).
```

Send a message to destination process identifier.

Wait for a response until timeout and return either the response or error.

Spawn actors running functions that message other actors.

# DISTRIBUTED ACTORS: TODAY'S DESIGN



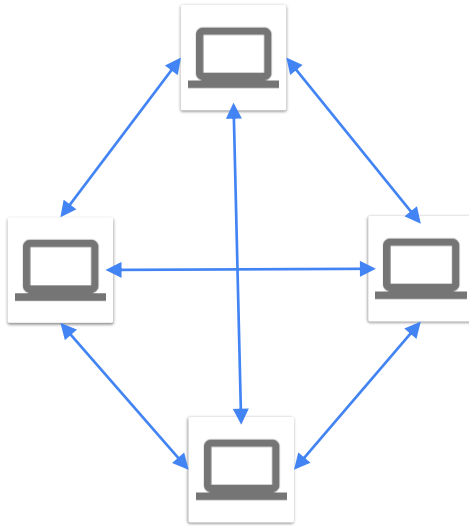
All nodes communicate with all other nodes.

- Nodes run actors that can communicate with other actors
- Transparent messaging

Nodes maintain open TCP connections.

- Heartbeat other nodes to detect failure
- Actors considered failure under partition or node failure

# DISTRIBUTED ACTORS: TODAY'S **DRAWBACKS**

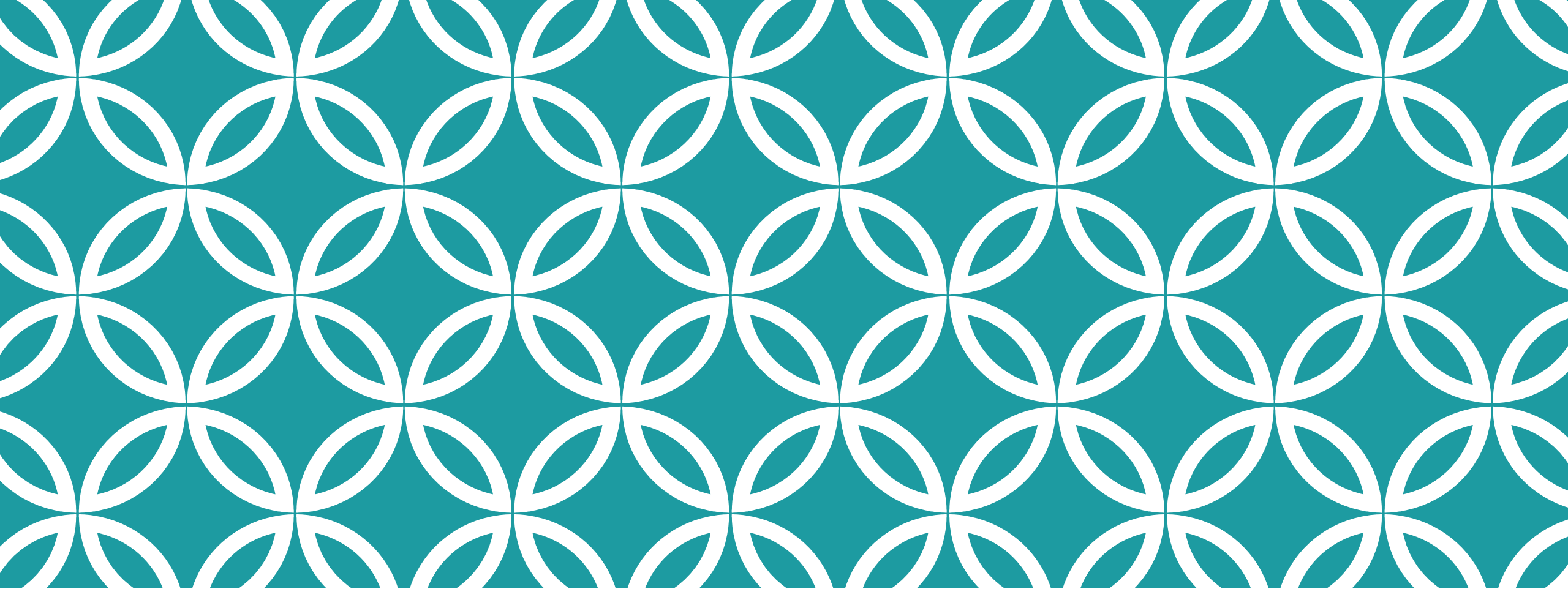


## Scalability

- All-to-all communication is expensive and prohibitive
- Nodes need to know about all other nodes

## Latency

- Multiplexed TCP connection is a bottleneck
- Many actors reduced to a single connection's speed
- Congestion:
  - network latency, queueing delay
- Contention:
  - competing for shared resources, slow-sender vs. fast-sender



# PARTISAN

Improving the scalability of  
distributed actor systems.

# PARTISAN

Design of an alternative runtime system for distributed actor systems

- Design and prototype implementation in Erlang

Runtime selection of communications overlay network

- Specialize overlay selection to communications pattern of application
- No modification to application code

Provides reduced latency and increased scalability

- Enable parallelism on the network
- Schedule messages efficiently on the network



# PARTISAN: API

Simple transformation for existing applications to use Partisan.

```
call(Dst, Msg, Timeout) ->  
  Dst ! Msg,  
  
  receive  
    Response ->  
    Response  
  after  
    Timeout ->  
    {error, timeout}  
  end  
end.
```



```
call(Dst, Msg, Timeout) ->  
  partisan_peer_service_manager:forward(Dst, Msg, []),  
  
  receive  
    Response ->  
    Response
```

1-to-1 correspondence in API

Feature	API	Analogous Call (Erlang)
Join node to cluster	join(Node)	net_kernel:connect_node(Node)
Remove self from the cluster	leave()	net_kernel:stop()
Return locally known peers	members()	nodes()
Forward message to registered name	forward(Node, Name, Msg, Opts)	erlang:send({Name, Node}, Msg)
Forward message to process id	forward(Pid, Msg, Opts)	erlang:send(Pid, Msg)

# CAVEAT EMPTOR

## References

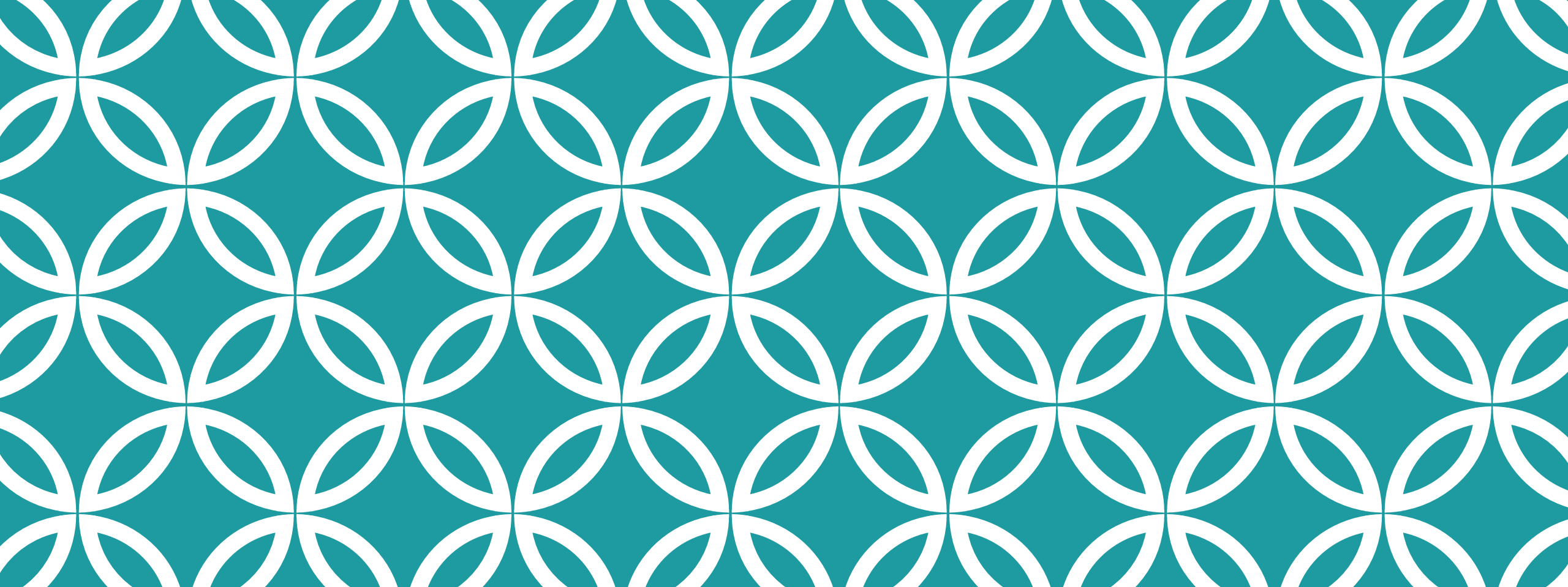
- Unique references generated by BEAM, guaranteed globally unique
- Not serializable presently because deserialization tied to Distributed Erlang
- **Lots of platform-agnostic alternatives:** Snowflake IDs, Logical Clock derivatives (HLC, etc.)

## Closures

- Subject of **my Ph.D. advisor's thesis**
- Serialization tied to Distributed Erlang
- When are these safe to capture?
- No support for sending closures at the moment

Hi!





# IMPROVING SCALABILITY

There's no "one-size-fits-all" overlay for distributed applications.

# OVERLAY SELECTION

## No “one-size-fits-all” topology

- Rigidity of the full-mesh overlay assumes one application design
- Not necessarily true for modern applications (mobile, IoT)

## Selection of overlay at runtime

- Select the runtime based on the communication pattern
- Full-mesh, **Client-server**, **Peer-to-peer**, Publish-subscribe.

## Tradeoffs

- Redundant, large-scale overlays more expensive in transmission but support more clients

```
{partisan, [% Enable affinity scheduling.
            {affinity, enabled},

            %% Enable parallel connections.
            {parallel, enabled},

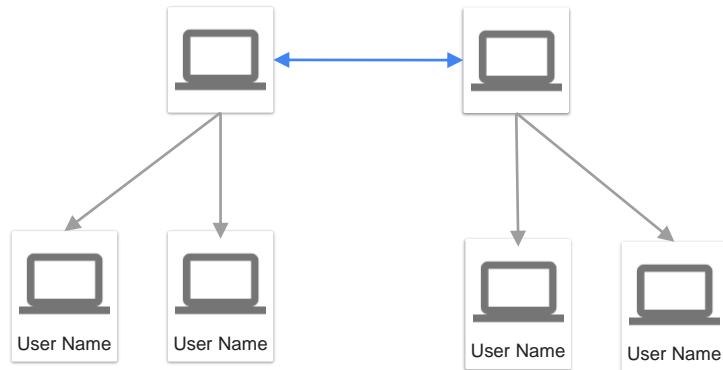
            %% Optional: override default.
            {parallel_connections, 16},

            %% Specify available channels.
            {channels, [vnode, gossip, broadcast]}},

%% Selection of overlay.
{membership_strategy,
 partisan_full_mesh_membership_strategy} ]}.
```

Select the overlay network desired.

# CLIENT-SERVER OVERLAY



Client nodes communicate with server nodes.

Server nodes communicate with one another.

Point-to-point messaging through the server.

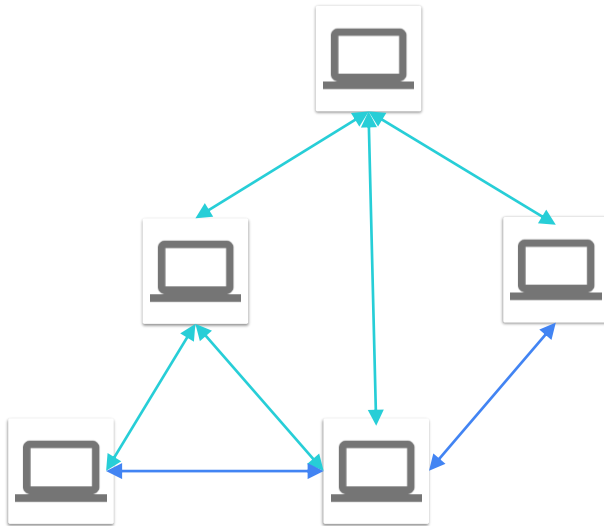
- Server routes messages on clients behalf

Nodes maintain open TCP connections.

- Considered “failed” when connection is dropped.

Typical communication pattern in **mobile** and **web** applications today.

# PEER-TO-PEER OVERLAY



Supports large-scale networks (10,000+ nodes)

- Built on existing protocols: HyParView, Plumtree, Cimbiosys

Nodes maintain partial views of the network

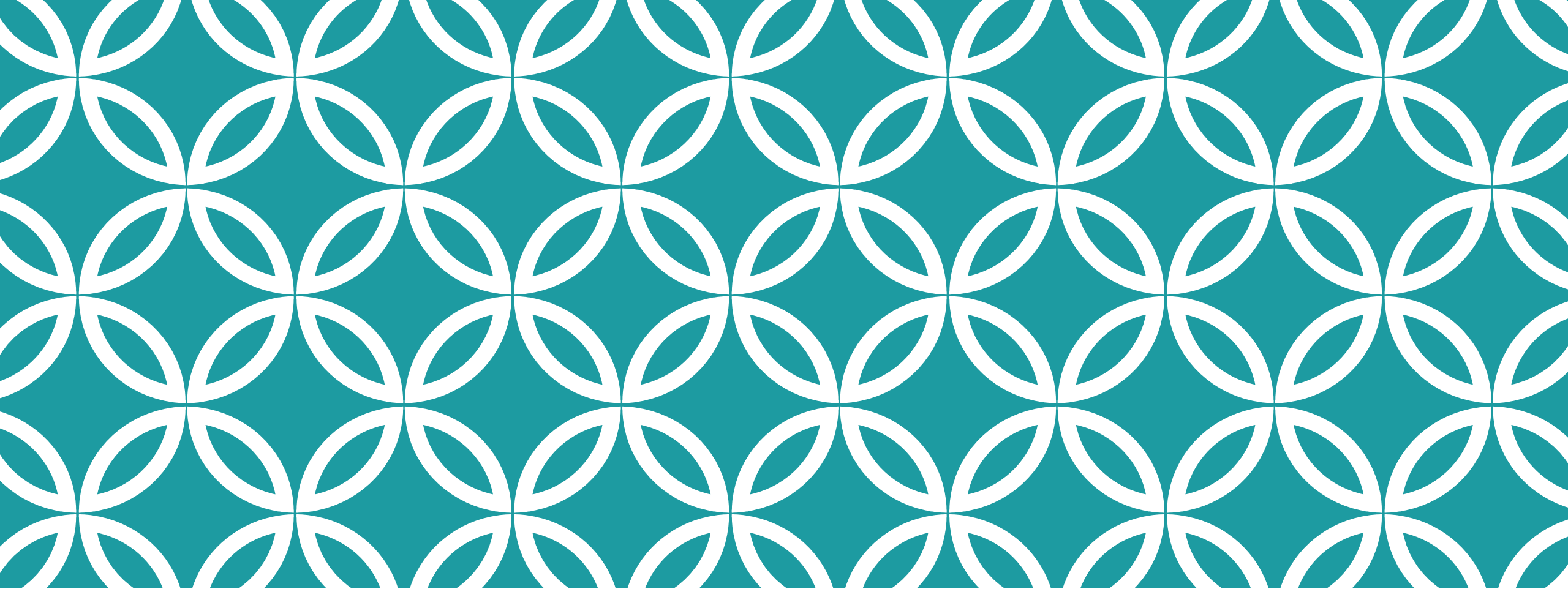
- **Active** views form connected graph
- **Passive** views for backup links used to repair graph under failure

Nodes maintain open TCP connections.

- Considered “failed” when connection is dropped.
- Some links to passive nodes kept open for “fast” replacement of failed active nodes

Point-to-point messaging for connected nodes.

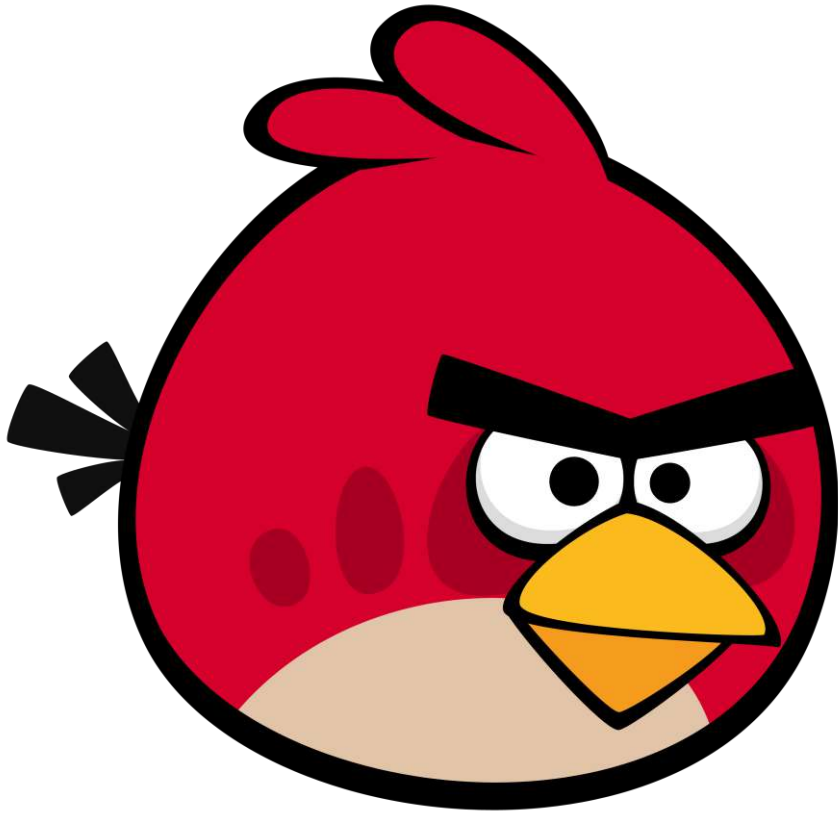
- Spanning tree lazily computed and used for routing messages transitively to the final recipient



# EVALUATING SCALABILITY

There's no "one-size-fits-all" topology for distributed applications.

# ROVIO / ANGRY BIRDS



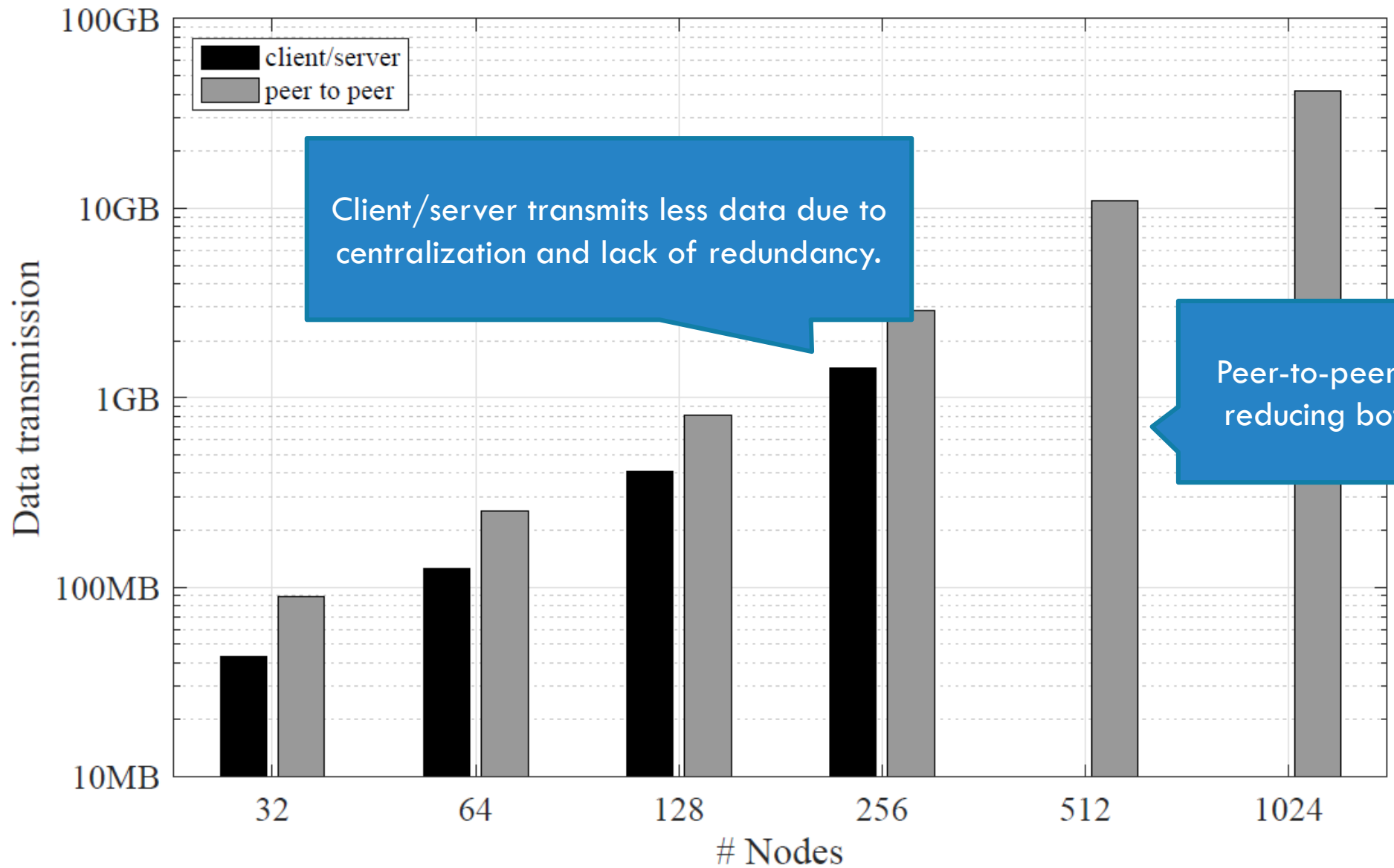
## Advertisement counter (SyncFree, EU-FP7)

- Each mobile device keeps track of a counter of times displayed
- Modeled as a convergent data structure for distributed counting
- Periodically, synchronizes with other peers
- Authored using the Lasp programming model (PPDP '15)

## Specialize the overlay network at runtime

- Evaluate which overlay can support the most clients
- Two evaluated: client-server vs. peer-to-peer
- Not evaluated: full-mesh (unrealistic for mobile application)





# SCALING LASP, P2P KVS: TRADEOFFS

# SUMMARY: IMPROVING SCALABILITY

Enables the use of actor systems for larger-scale applications

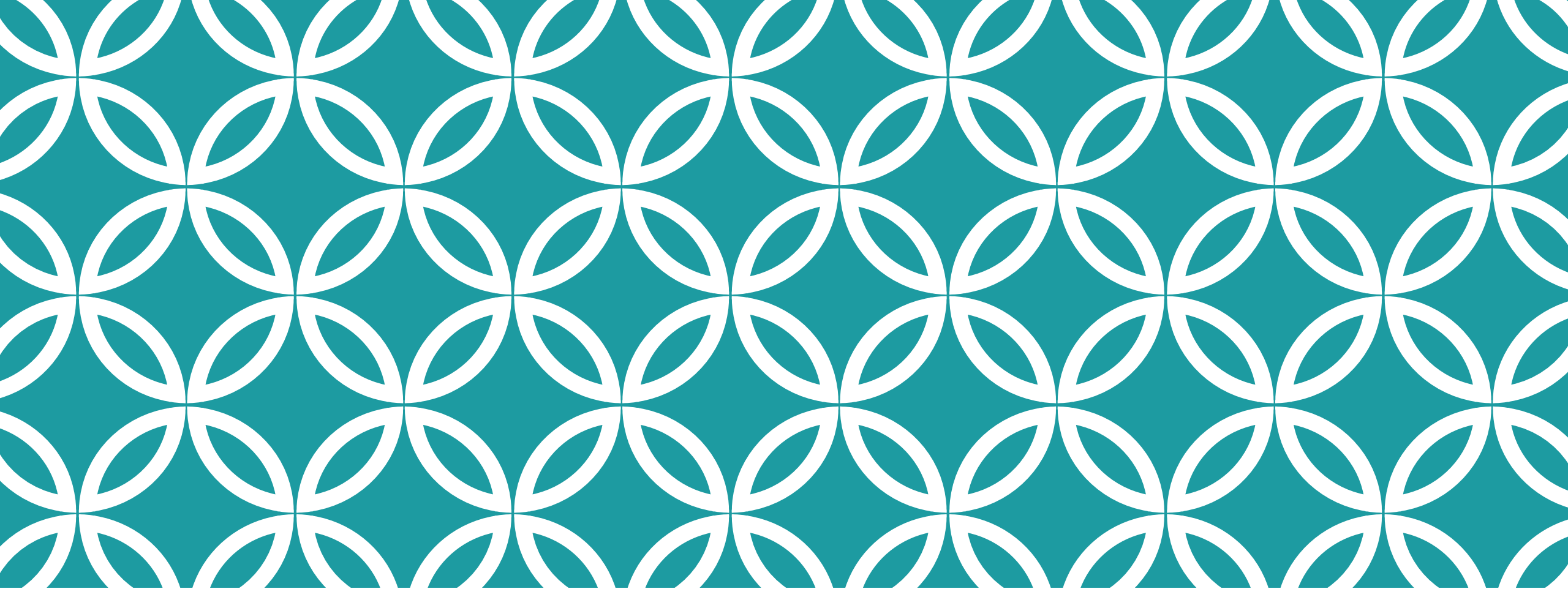
- Different overlays enable larger number of clients
- Overlays allow more traditional communication patterns for mobile applications
- May be suitable for “Internet of Things” applications

Performance optimizations

- Supported by all topologies

Prototype

- Peer-to-peer topology adopted by community members
- Used on hardware devices in LightKone EU-H2020 project on edge computing



# IMPROVING LATENCY

Techniques for latency reduction by enabling parallelism of the network.

# IMPROVING LATENCY

## Head-of-line blocking

- Background cluster messages for maintenance, failure detection, cluster membership, etc.
- Application-behavior blocked and/or delayed

## Queueing delay

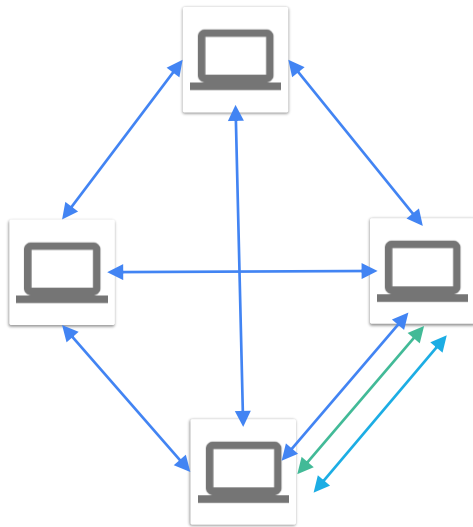
- Fast-senders vs. slow senders
- High-latency: delay in transmission, when available bandwidth for parallelism
- Large-payload: other senders are blocked during transmission and serialization/deserialization

## Can we use knowledge from actors?

- Act sequentially
- Have identities and send to actors by identity

# NAMED CHANNELS

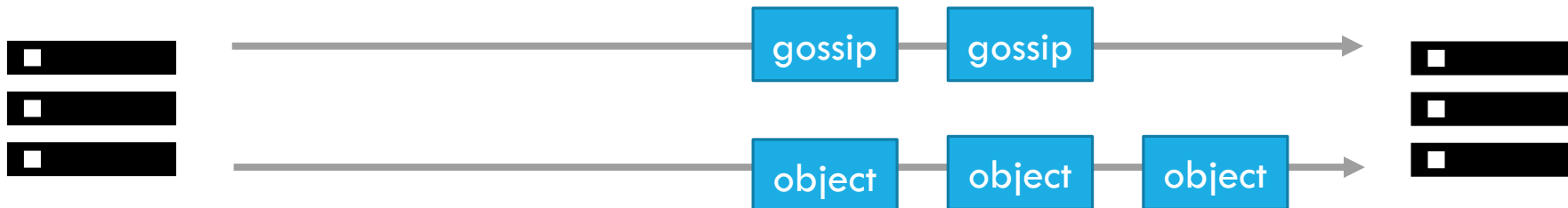
All we require is programmers to **annotate the type** of message when sending a message to another actor.



Enable multiple TCP connections between nodes for segmenting traffic.

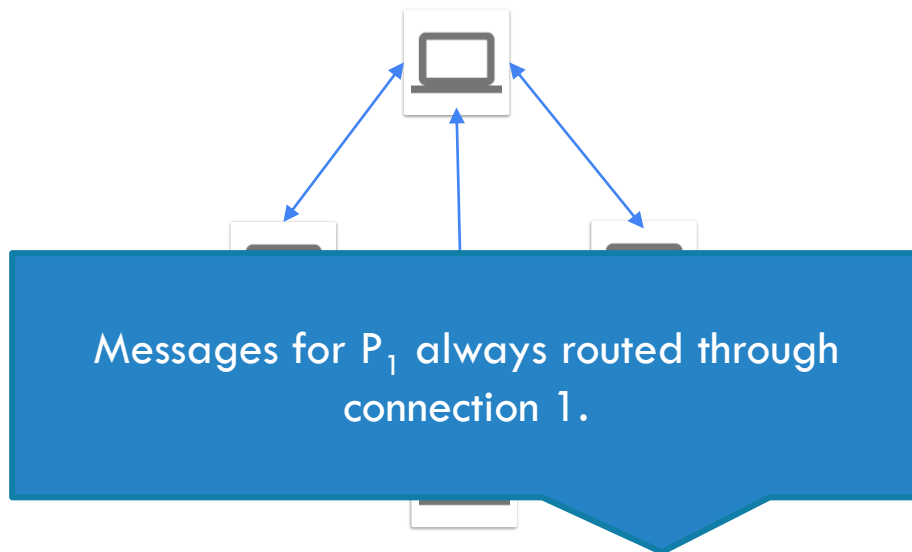
Alleviates head-of-line blocking between different types of traffic and destinations.

Beneficial for isolating background maintenance traffic from application-specific traffic.



# AFFINITIZED PARALLELISM

**Automatic**, given process identifier or with an **annotation** from the programmer if using a different key.

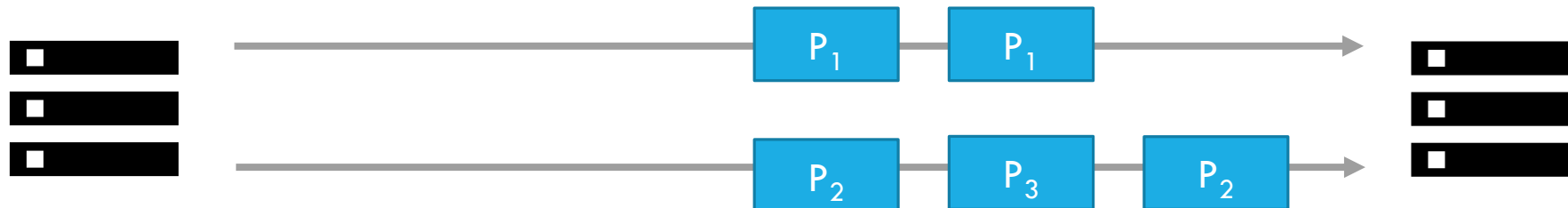


Enable multiple TCP connections between nodes for increased parallelism.

Partition traffic using a partition key.

- Automatic placement (using process identifier)
- Manual partitioning (using user-specified partition key)

Beneficial for separating slow-senders from fast-senders



# PROGRAMMER ANNOTATIONS

## Channels

- Specify channel name

```
-import(partisan_peer_service_manager, [forward/3]).
```

```
%% Specify channel.
```

```
forward(Dst, Msg, [ {channel, Channel} ]).
```

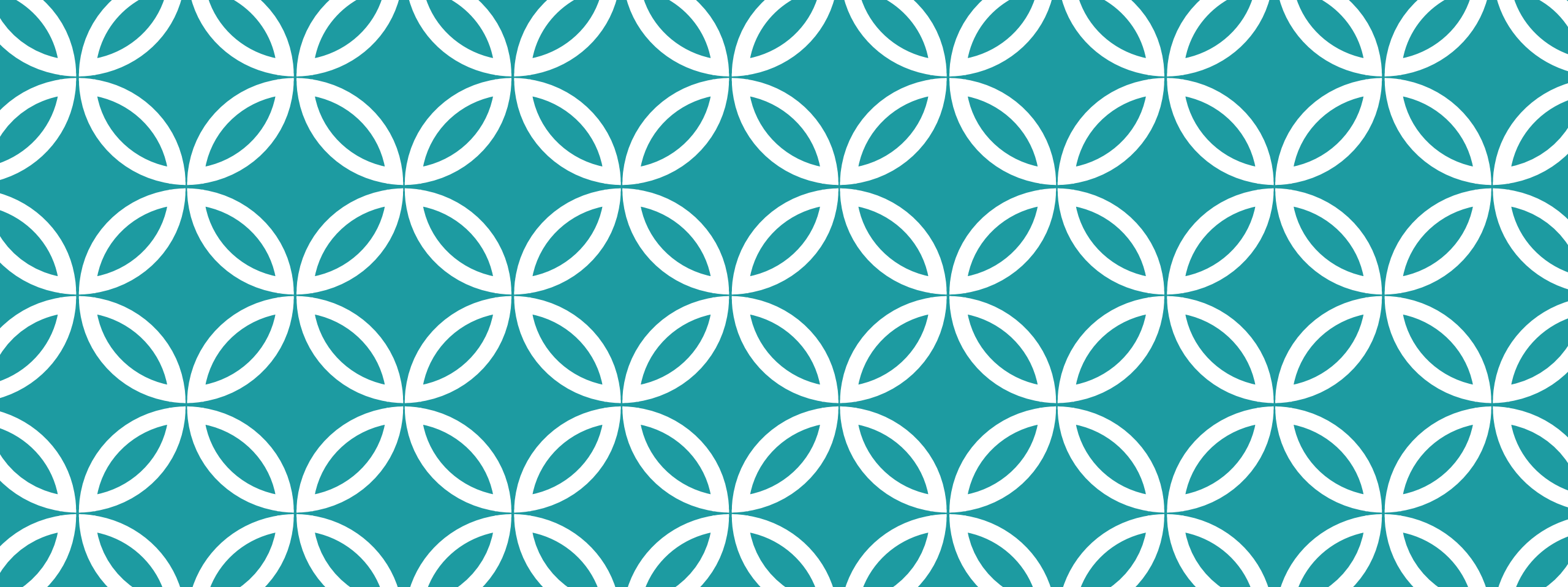
## Affinitized scheduling

- Specify partition key

```
%% Override key for affinity.
```

```
forward(Dst, Msg, [ {partition_key, Key} ]).
```

Override parameters, if necessary.

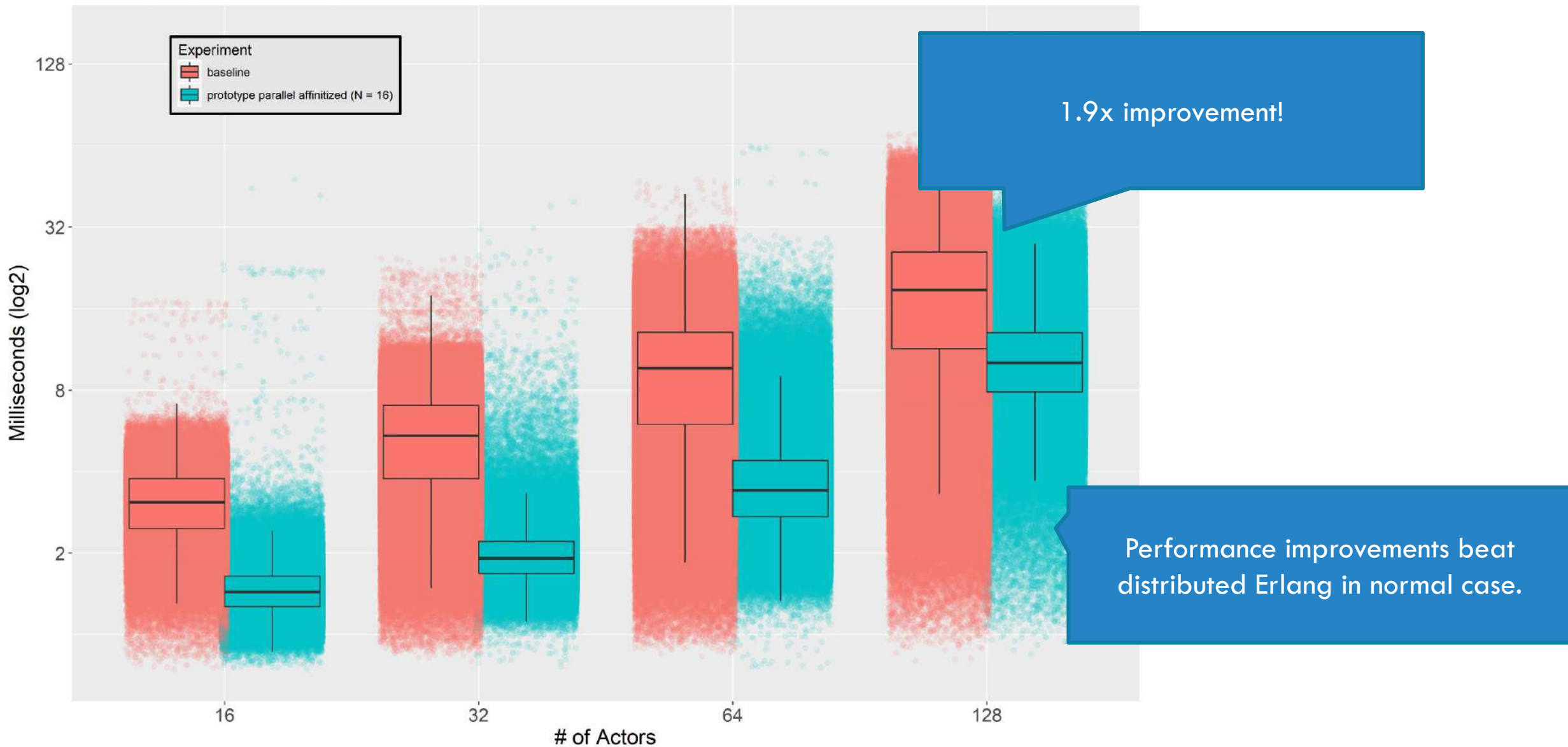


# EVALUATING LATENCY

Techniques for latency reduction  
by enabling parallelism on the  
network.

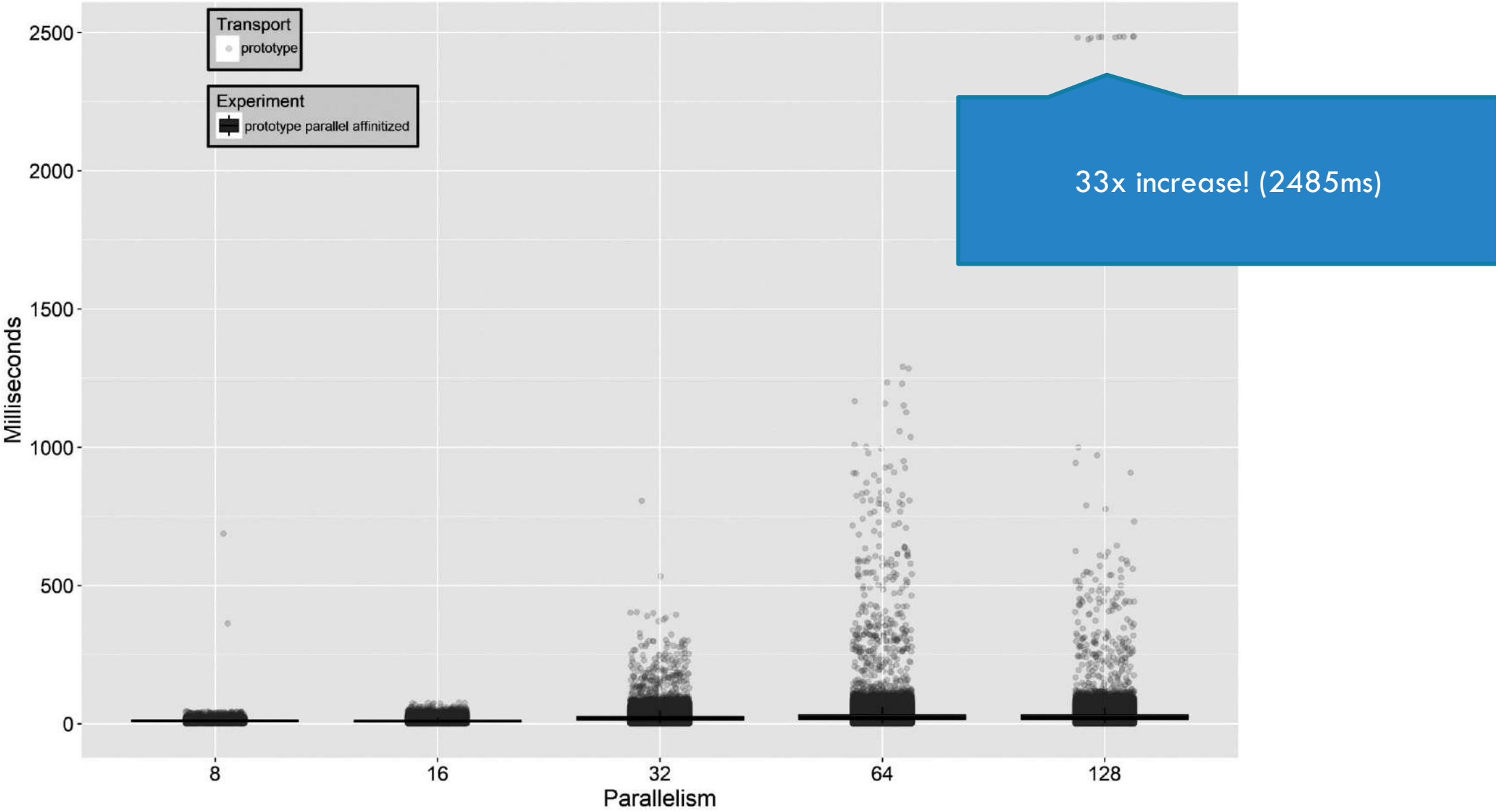


512KB Payload, 1ms RTT Latency



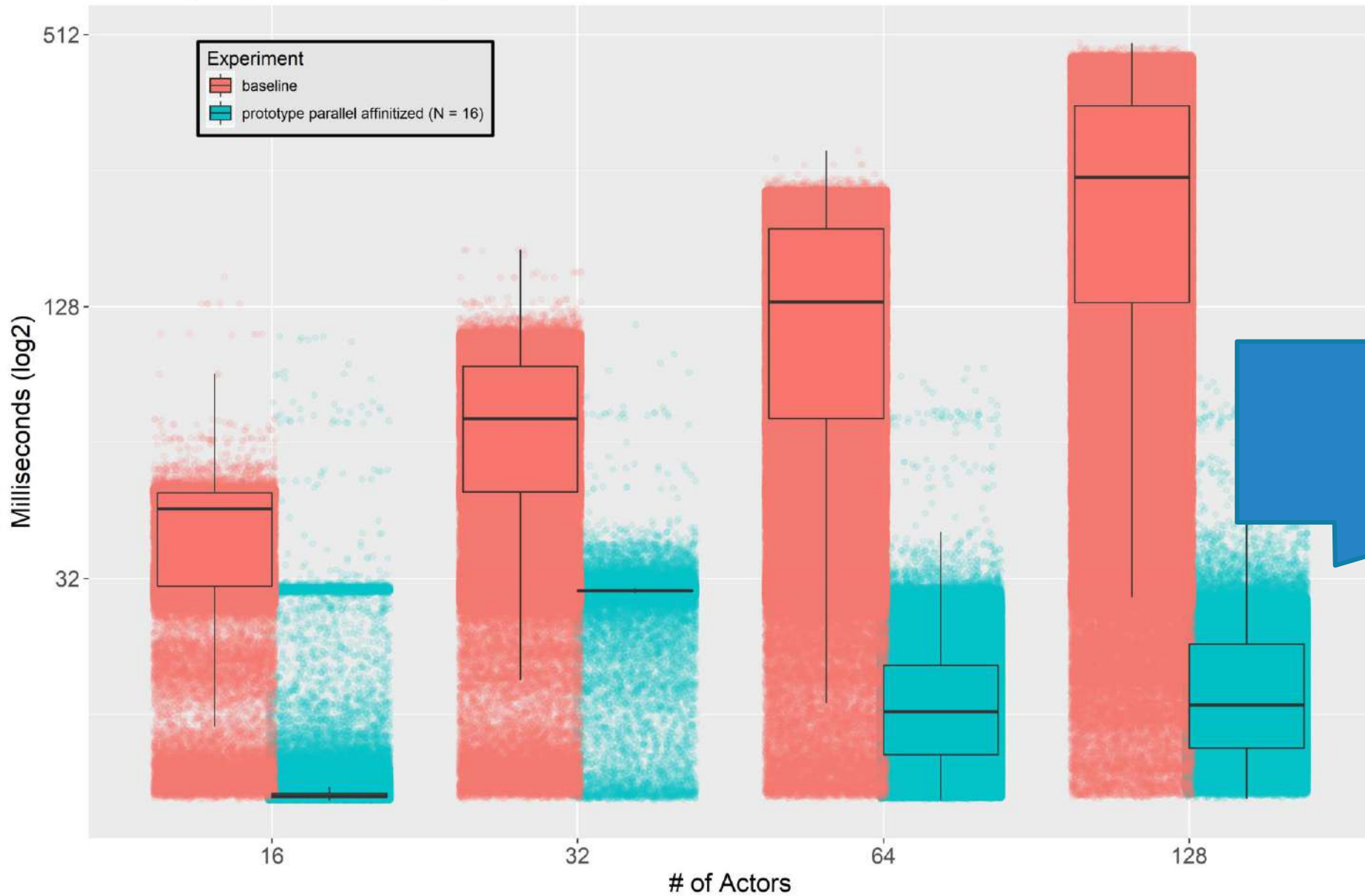
**BASELINE VS. OPTIMAL PERFORMANCE: 1MS**

512KB Payload, 1ms RTT Latency, 128 Actors



# QUEUE MAINTENANCE OVERHEAD

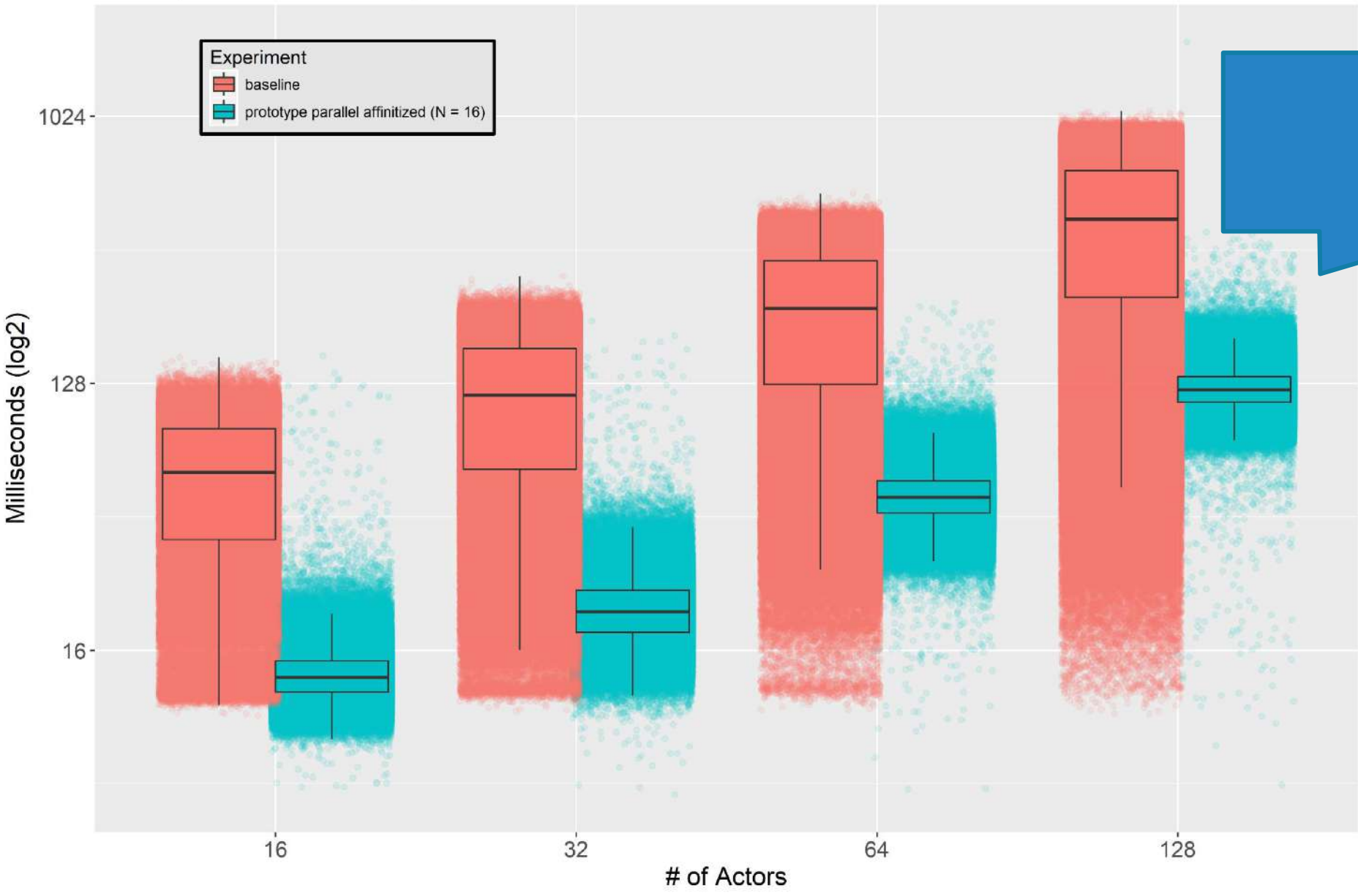
512KB Payload, 20ms RTT Latency



13.4x improvement!

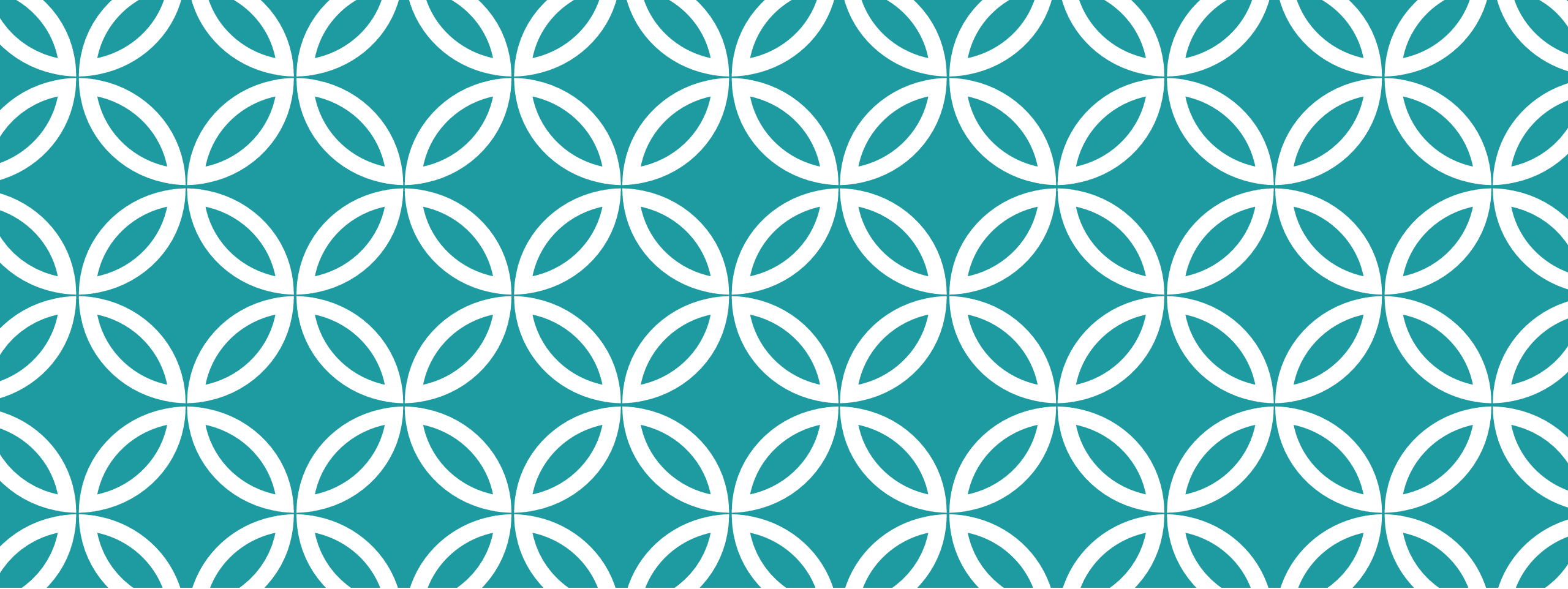
**INCREASED LATENCY MESSAGING: 20MS**

8MB Payload, 1ms RTT Latency



3.7x improvement!

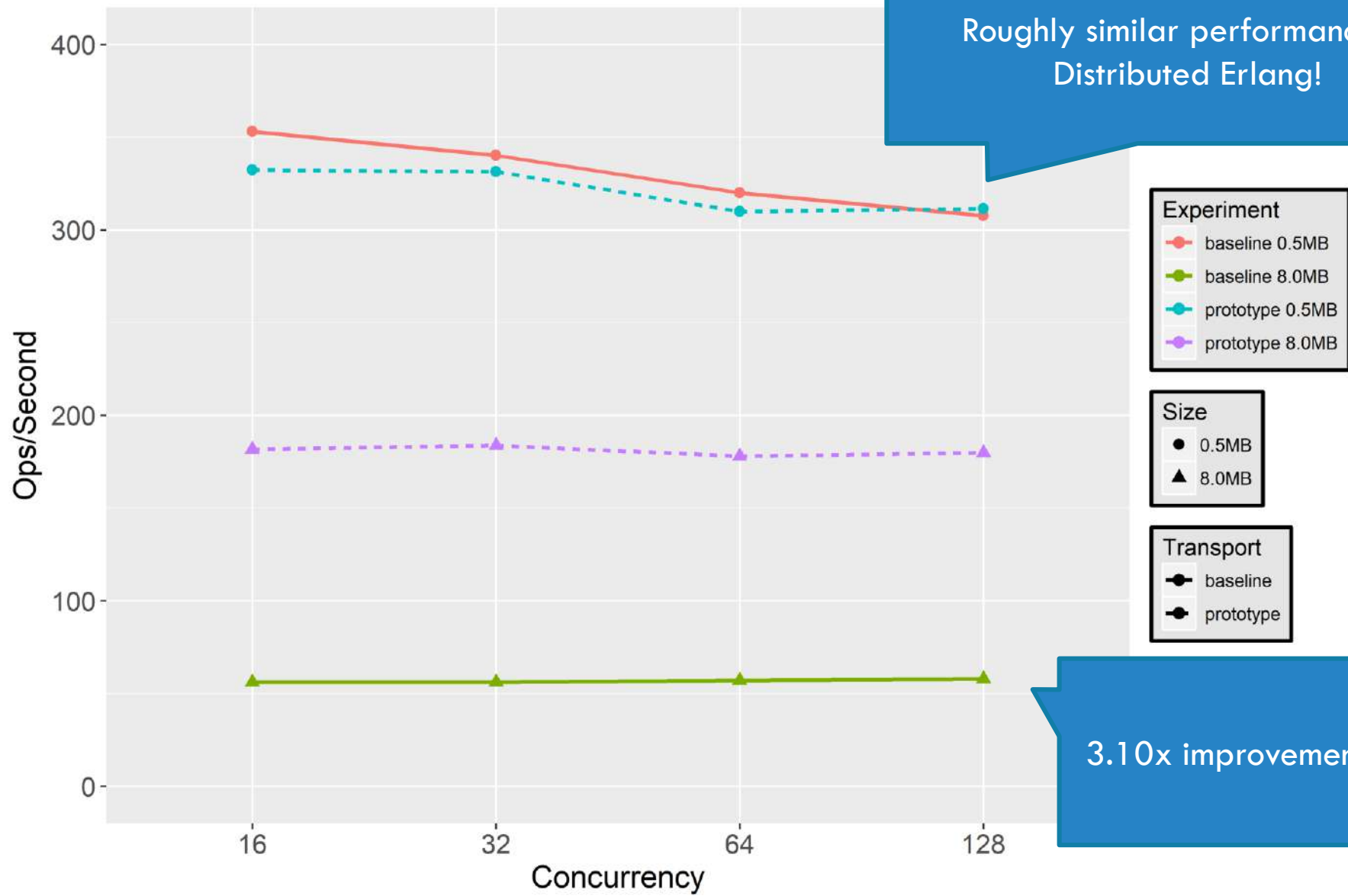
**INCREASED PAYLOAD MESSAGING: 8MB**



# EVALUATING LATENCY: RIAK CORE

Techniques for latency reduction by enabling parallelism on the network.

512KB/8MB, 1ms RTT Latency, Echo Throughput

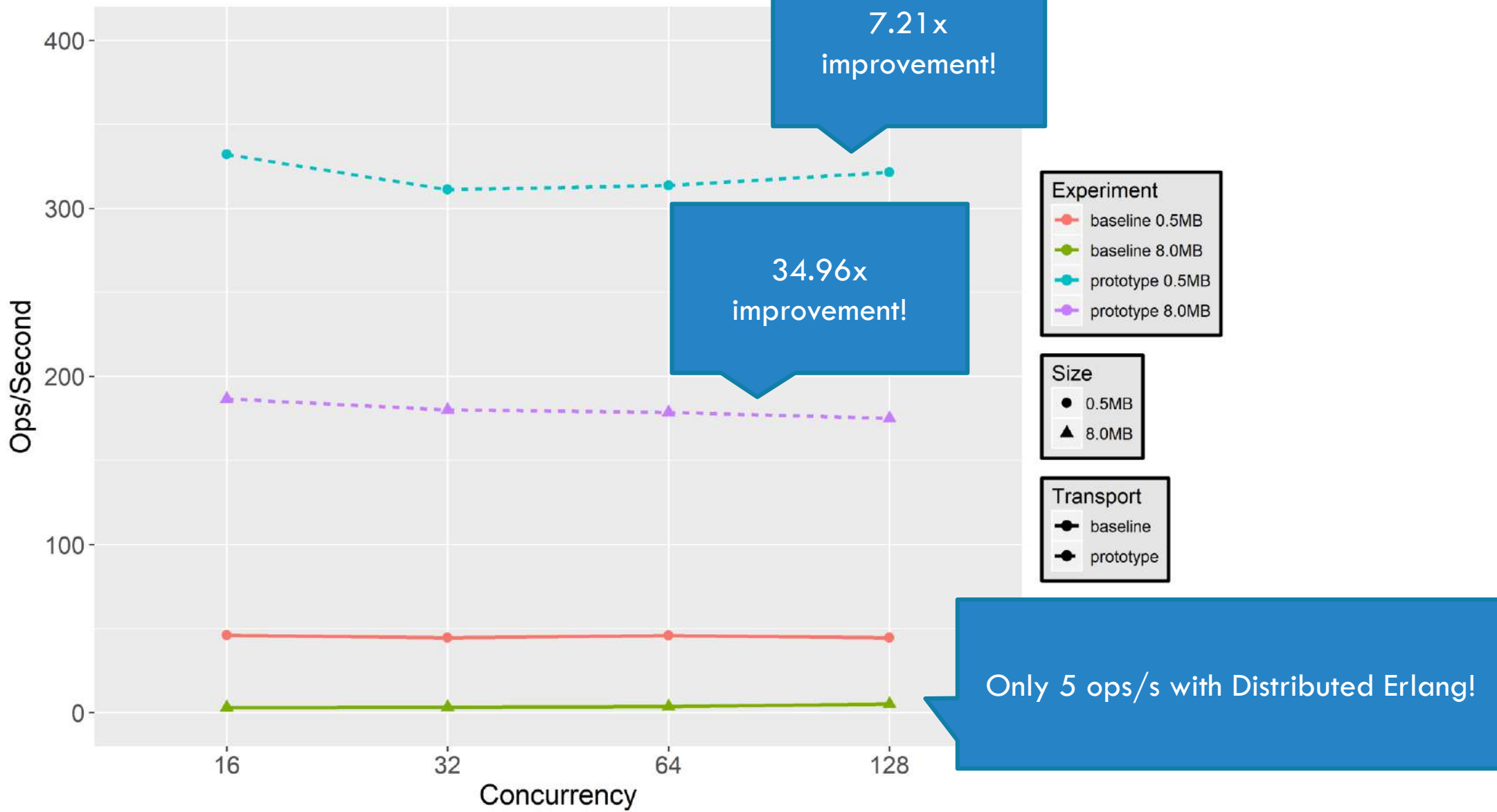


Roughly similar performance to Distributed Erlang!

3.10x improvement!

# ECHO SERVICE: 1MS

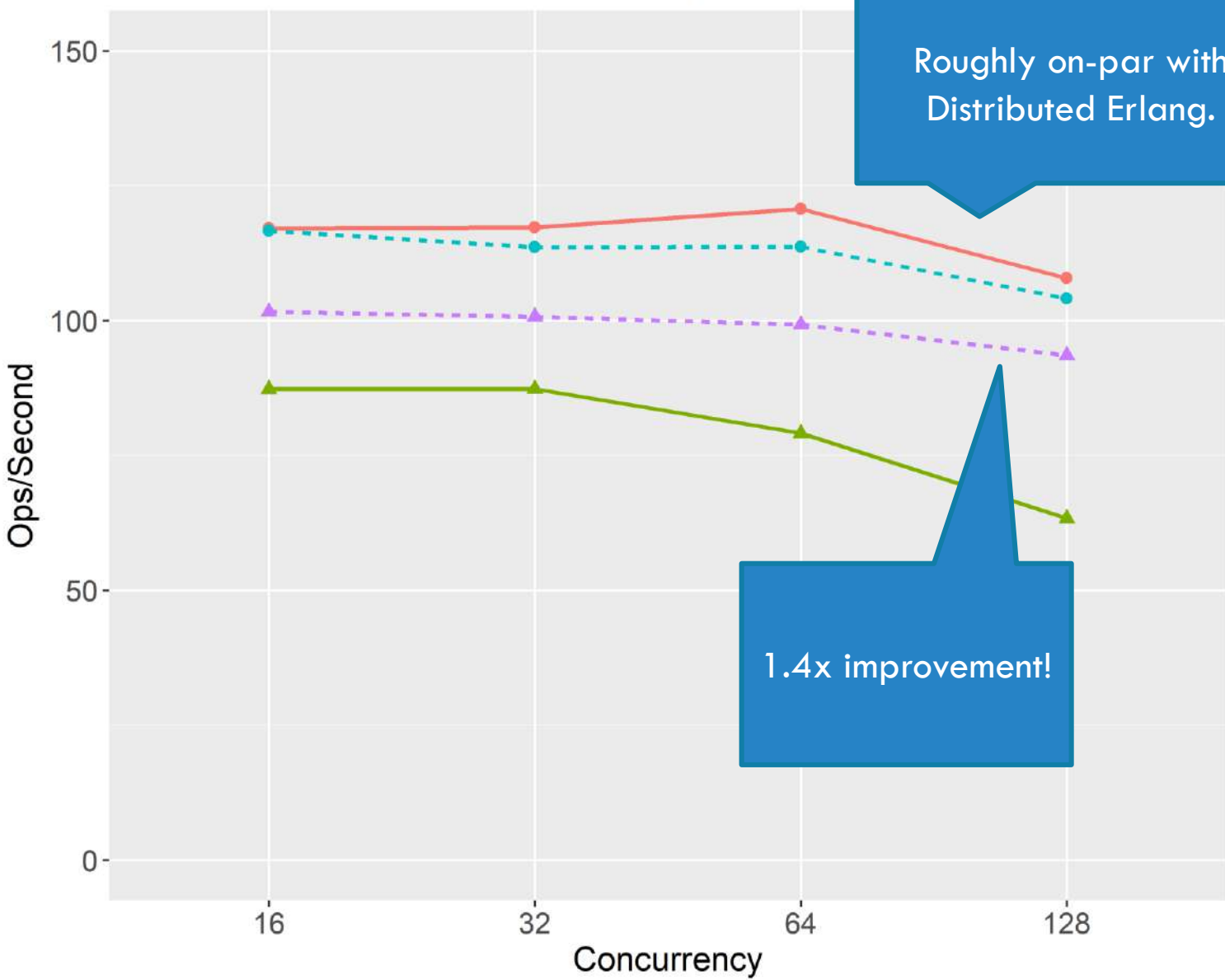
512KB/8MB, 20ms RTT Latency, Echo Throughput



# ECHO SERVICE: 20MS



512KB/8MB, 1ms RTT Latency, KVS Throughput



Roughly on-par with Distributed Erlang.

1.4x improvement!

**Experiment**

- baseline 0.5MB
- baseline 8.0MB
- prototype 0.5MB
- prototype 8.0MB

**Size**

- 0.5MB
- 8.0MB

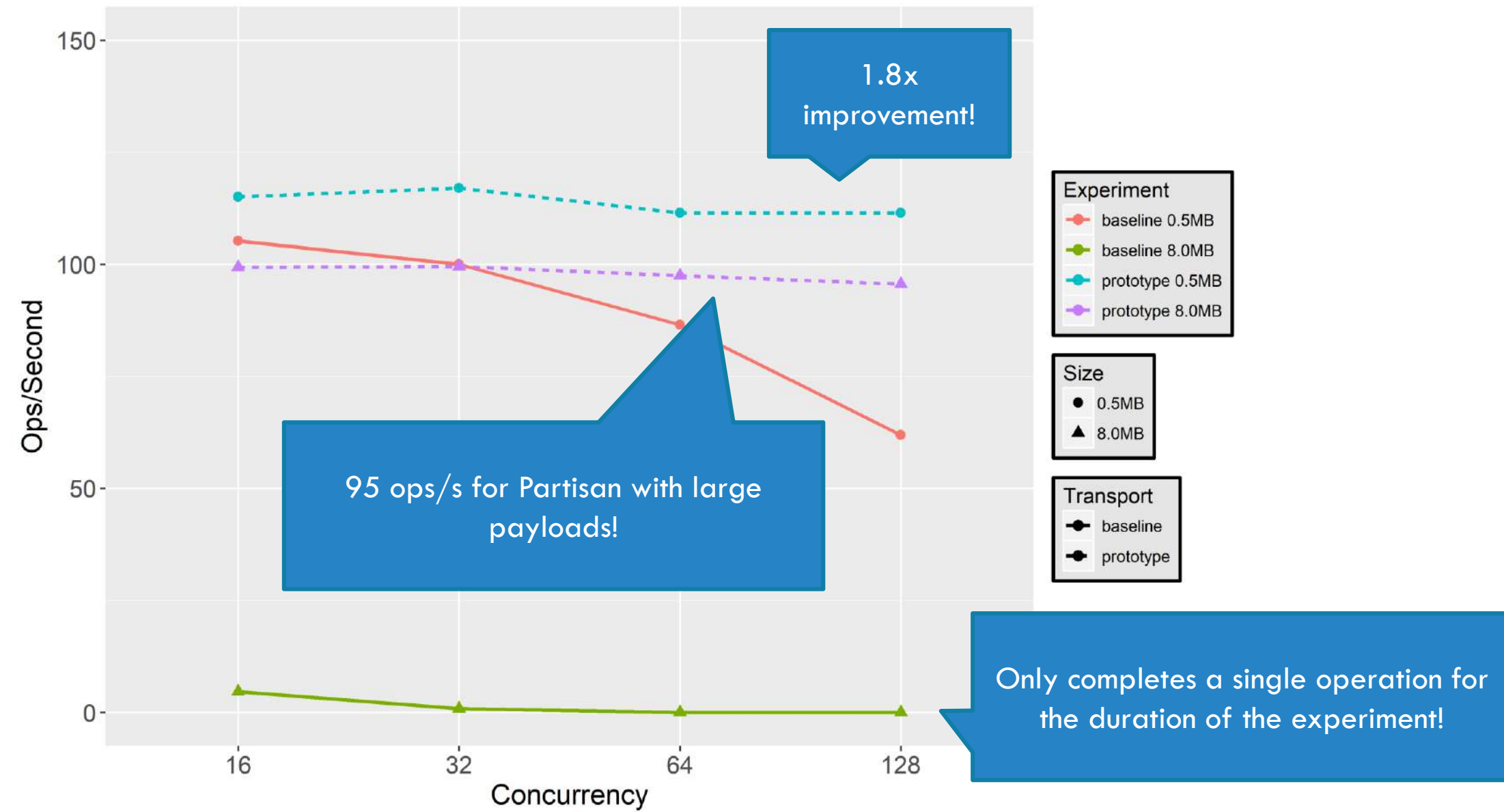
**Transport**

- baseline
- prototype

**KVS SERVICE: 1MS**



512KB/8MB, 20ms RTT Latency, KVS Throughput



**KVS SERVICE: 20MS**

# SUMMARY: IMPROVING LATENCY

## Performance on-par with Distributed Erlang

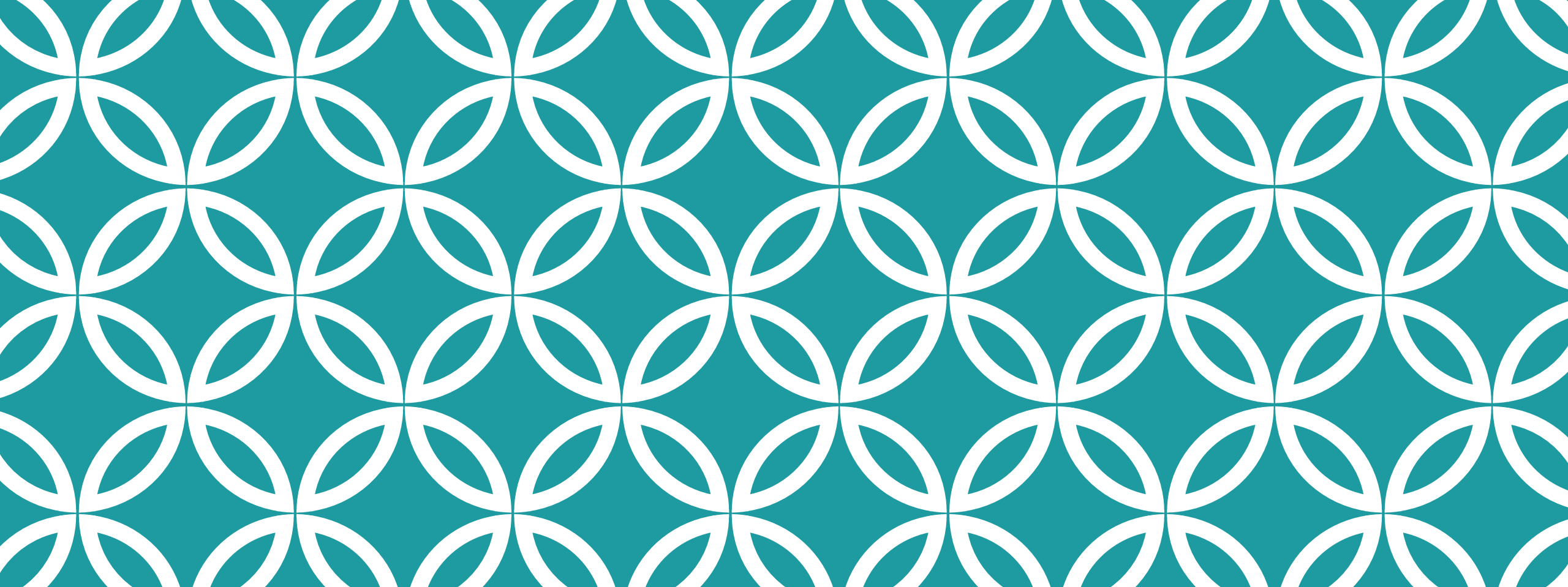
- Can achieve similar, if not better, performance in designed case
- Distributed Erlang is designed for single AZ/region

## Enable new types of applications

- Large data-centric workloads
- Geo-distributed applications (multi-AZ, possibly multi-region)
- Combination of both

## Prototype

- Validated on real-world programming framework
- Some adoption of our library



# PARTISAN V3

What's coming in the next version of Partisan?



# PARTISAN V3 IMPROVEMENTS

## Membership Strategies

- DSL for implementing membership protocols
- 3 implementations: Scamp, HiScamp (in progress), Cyclon
- Connection maintenance is automatic, user only has to handle membership events

## Orchestration

- Auto-clustering using Mesos, Docker Compose or Kubernetes
- Partisan will automatically discover peers and cluster them

## Example Applications

- 2PC, 2PC+CTP, 3PC, Gossip (3 variants)

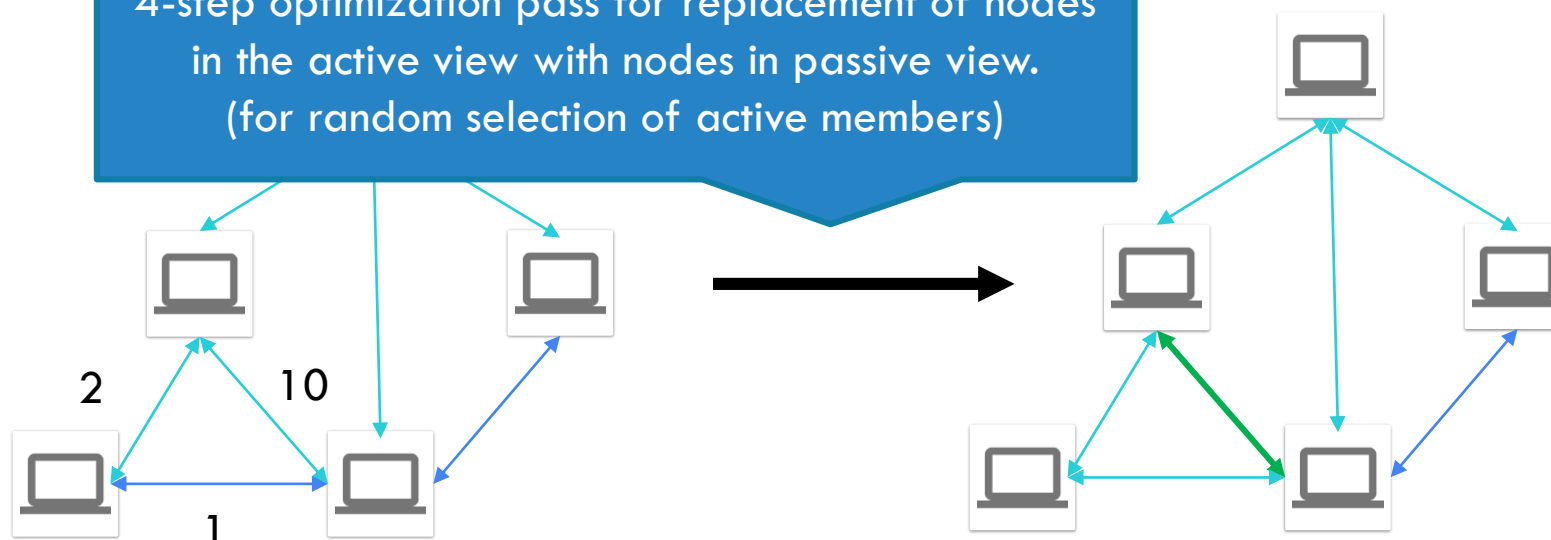
## Performance and bugs fixes.

- Many performance improvements and bug fixes



# X-BOT: ORACLE OPTIMIZED OVERLAYS

4-step optimization pass for replacement of nodes in the active view with nodes in passive view.  
(for random selection of active members)



Not all links have equal cost – with cost determined by outside “oracle.”

Reduce dissemination latency by optimizing overlay accordingly – swap passive and active members.

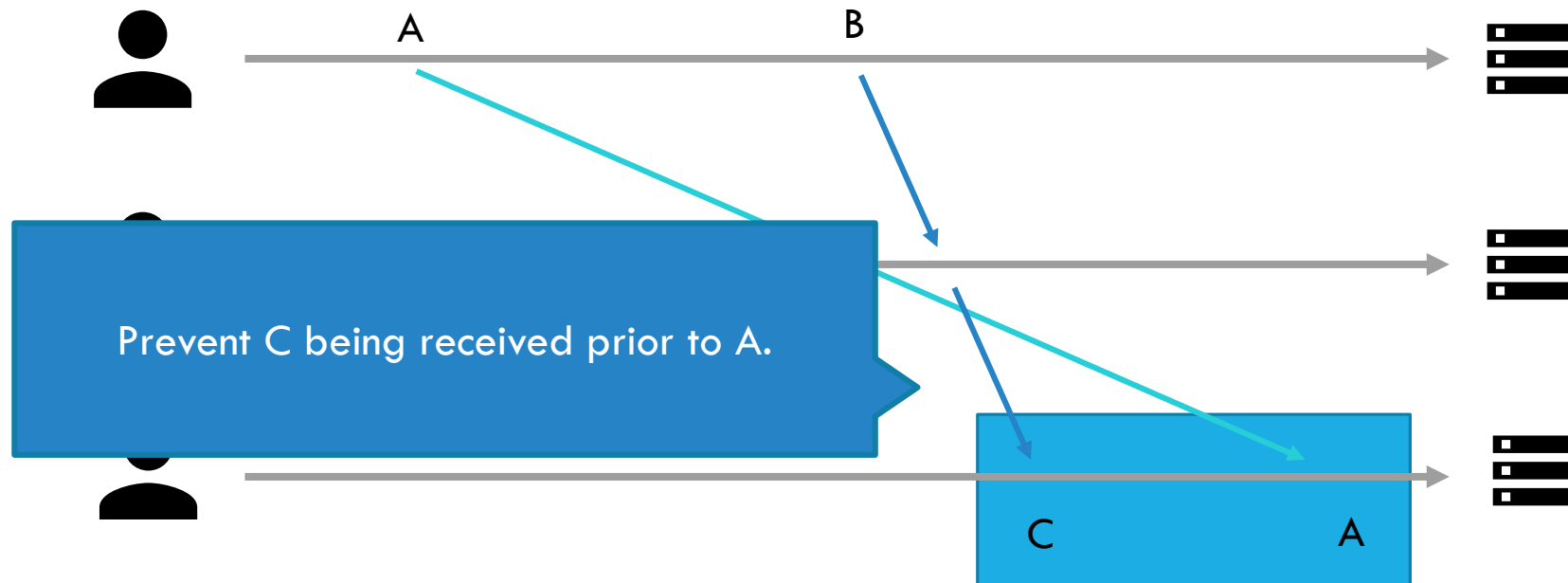


# CAUSAL ORDERING

Ensure messages are delivered in causal order

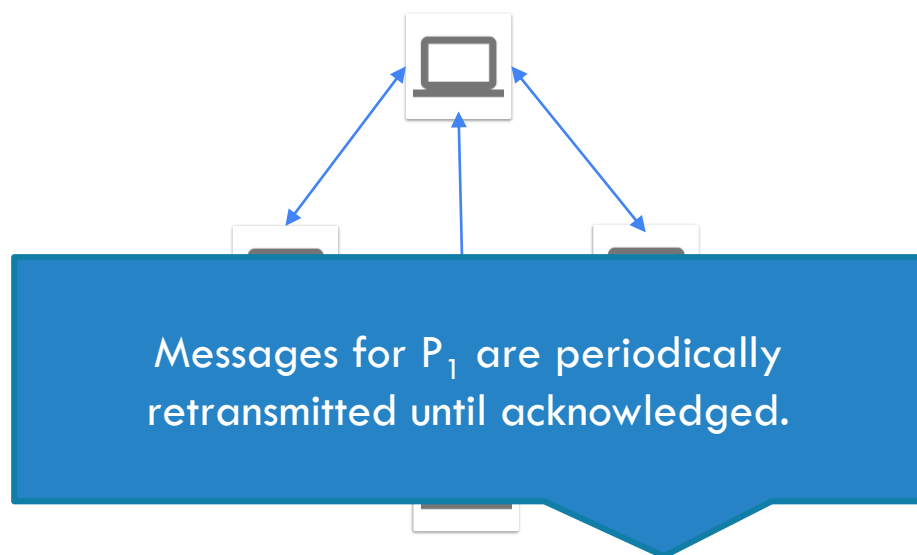
- FIFO between process pairs of sender/receiver
- Holds transitively for sending and receiving messages

Important for overlays where message might not always take the same path!  
(ie. HyParView, etc.)





# RELIABLE DELIVERY

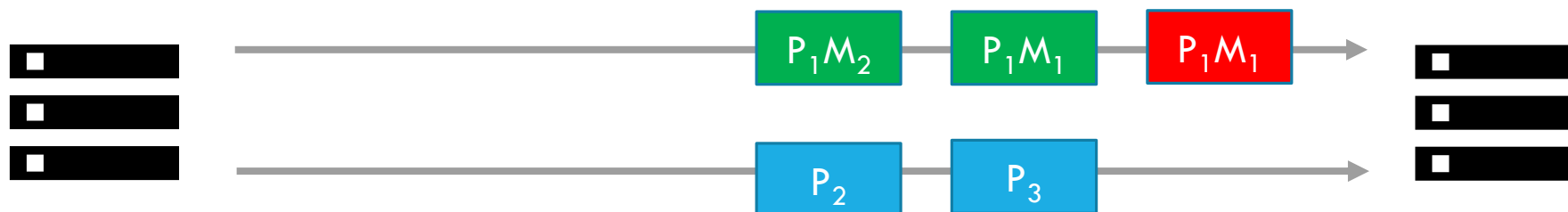


Buffer and retransmit messages using acknowledgements from destination

Per-message or per-channel

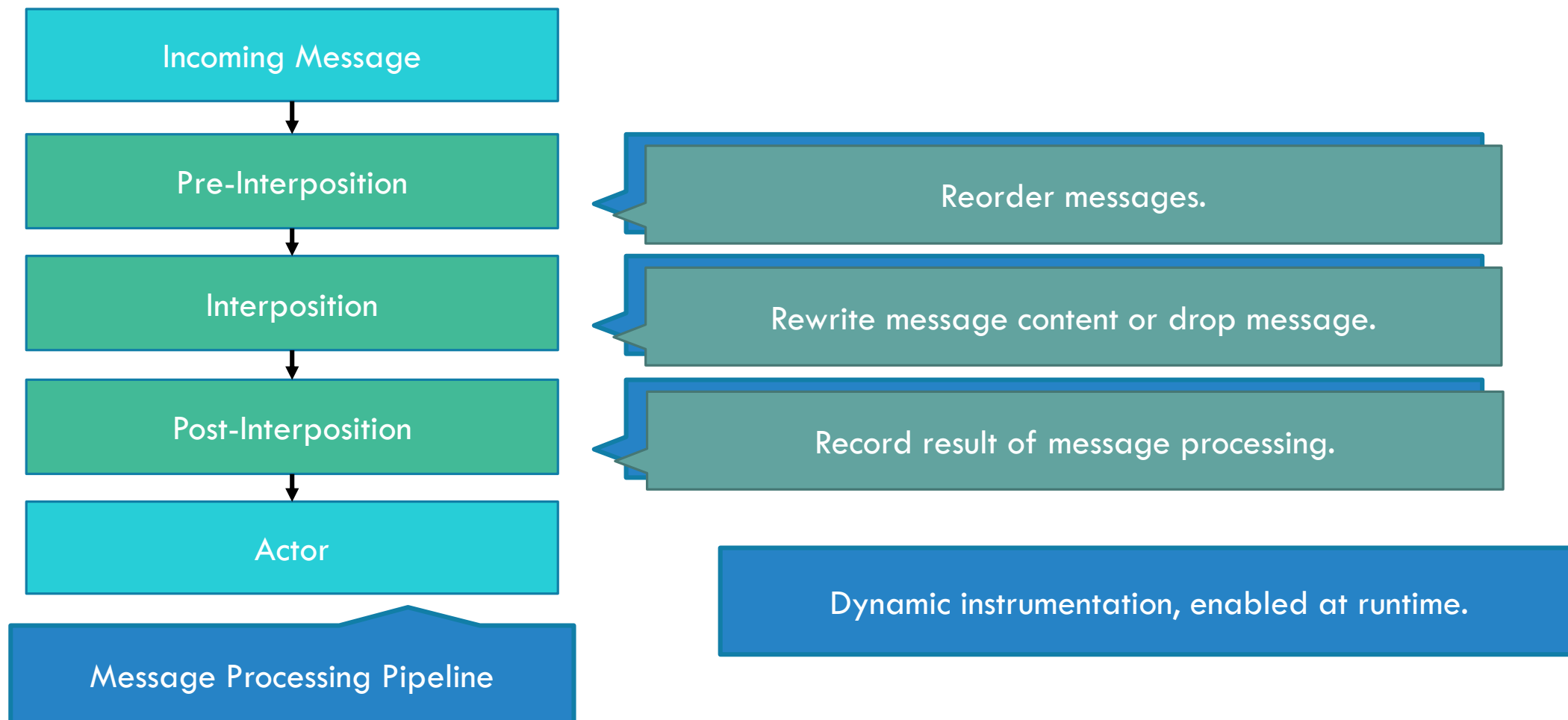
At-least-once delivery (to the application)

Needed for causal delivery where a dropped message might prohibit progress



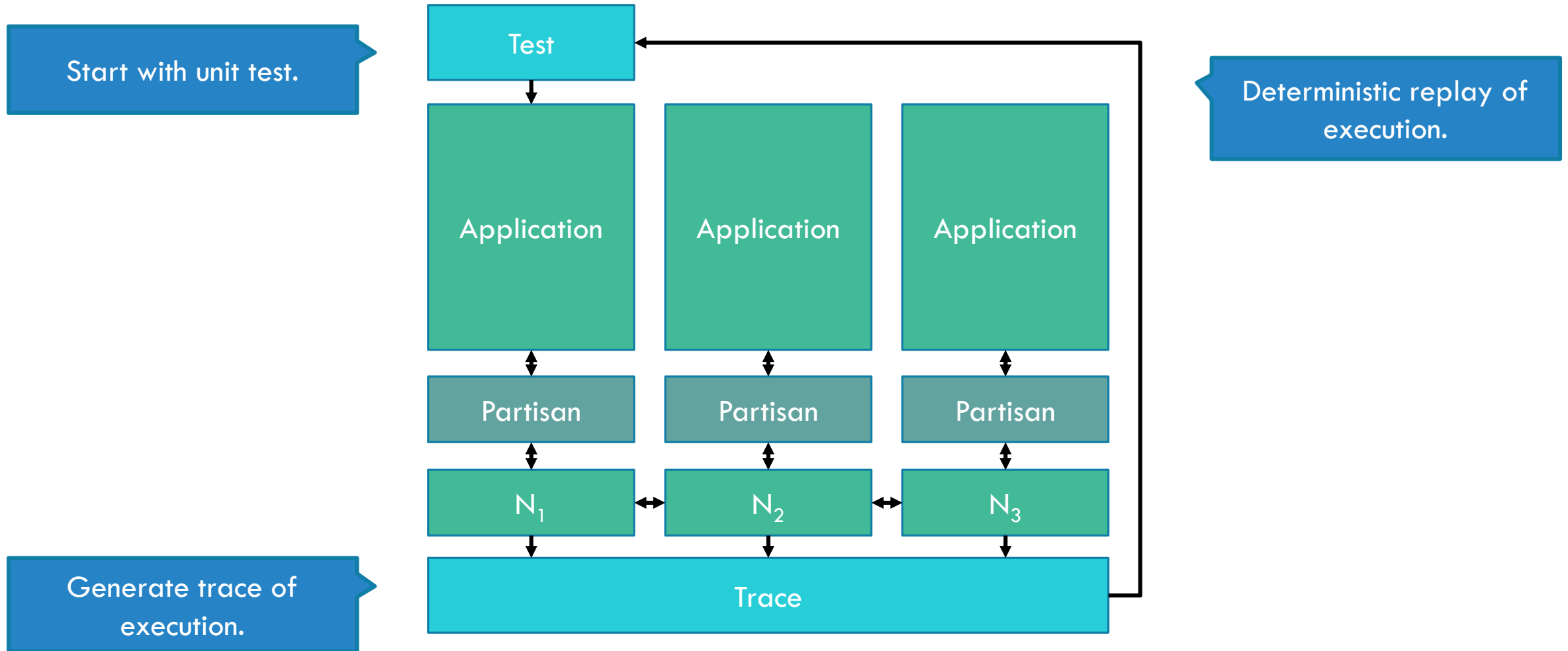


# MESSAGE INTERPOSITION





# TRACING, DEBUGGING AND REPLAY

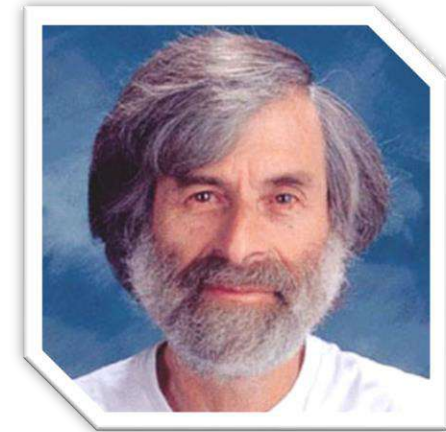


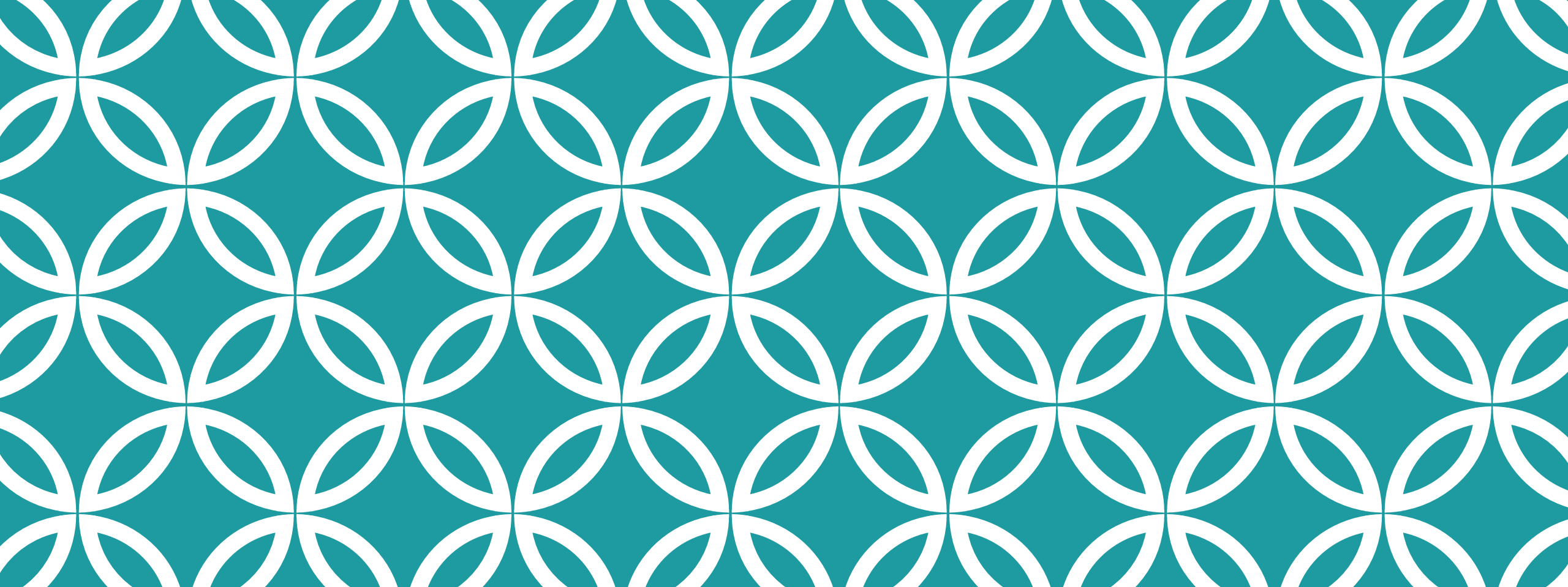


Distributed applications are ubiquitous, everyone's writing them!

However, distributed applications are still very difficult to write because servers can crash and messages can be lost!

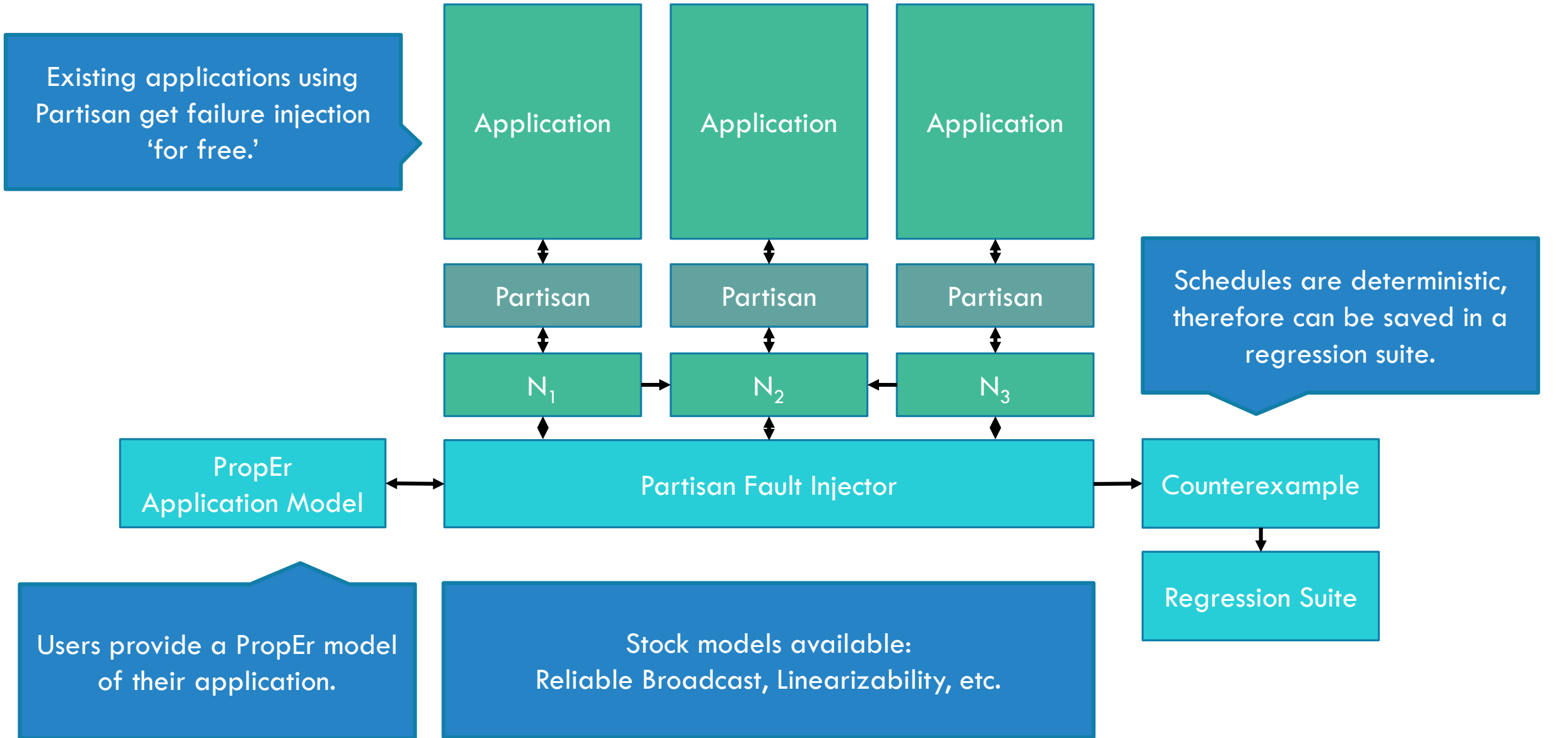
Do you know what your application will do if a **message is lost**? What if the application server **crashes** in the middle?

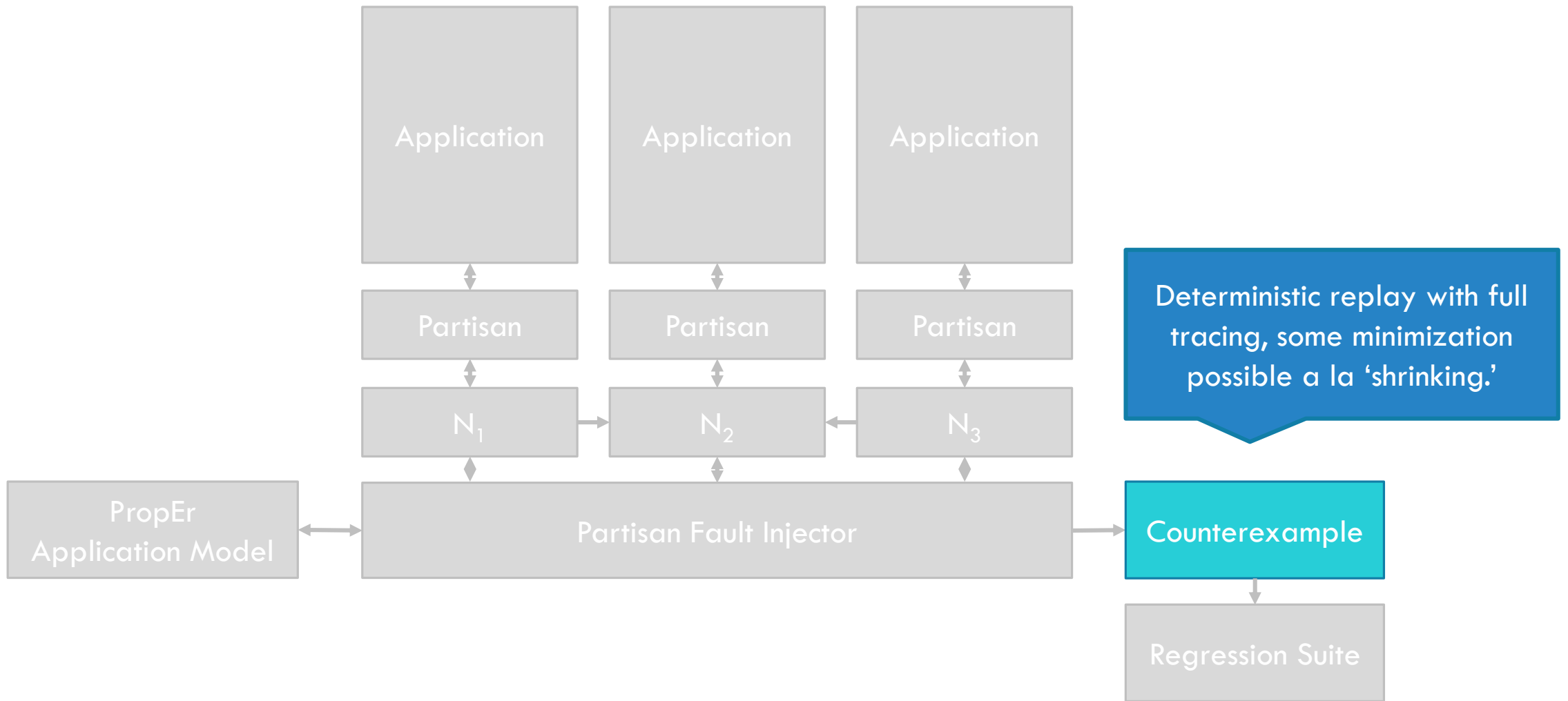


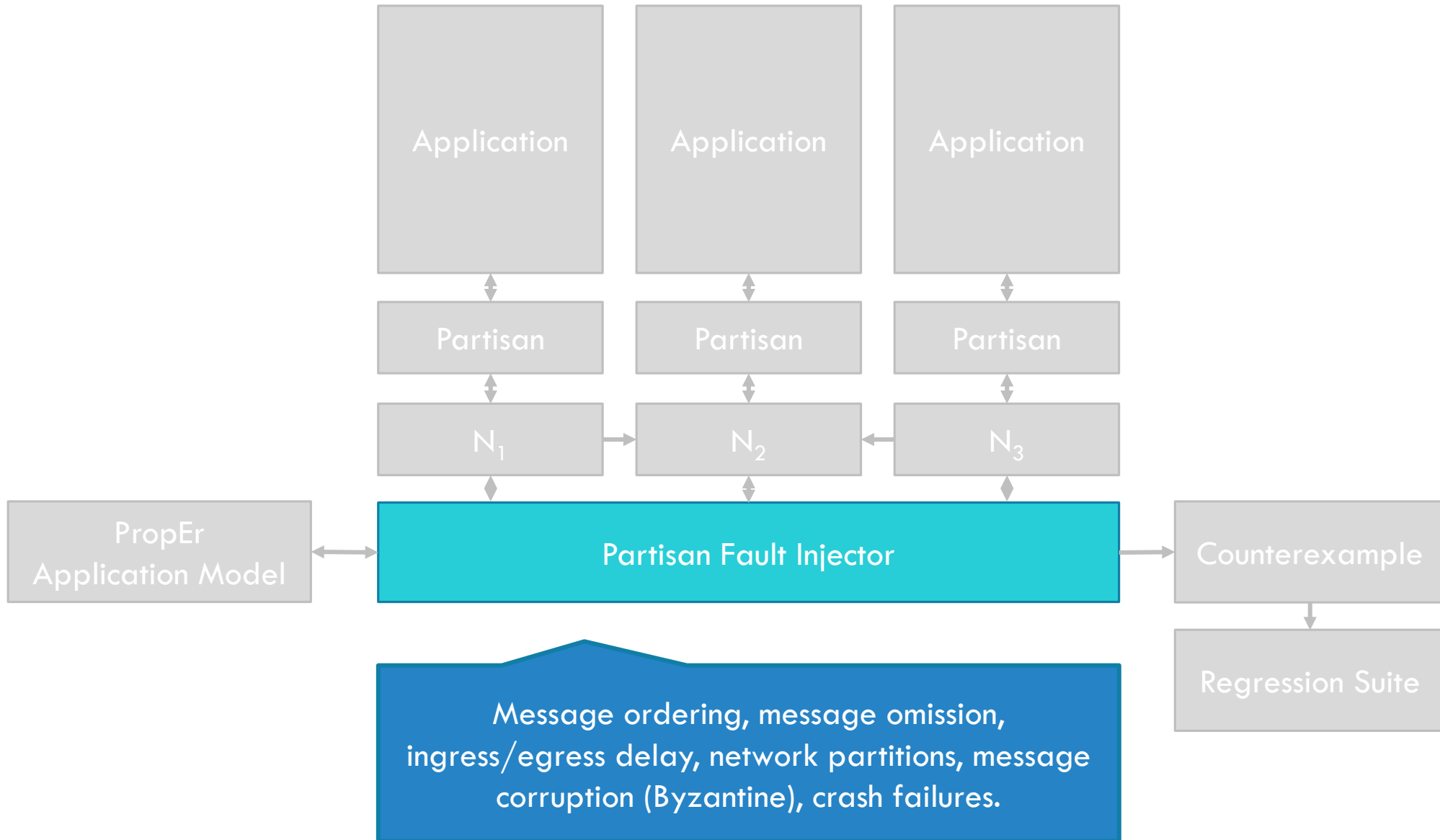


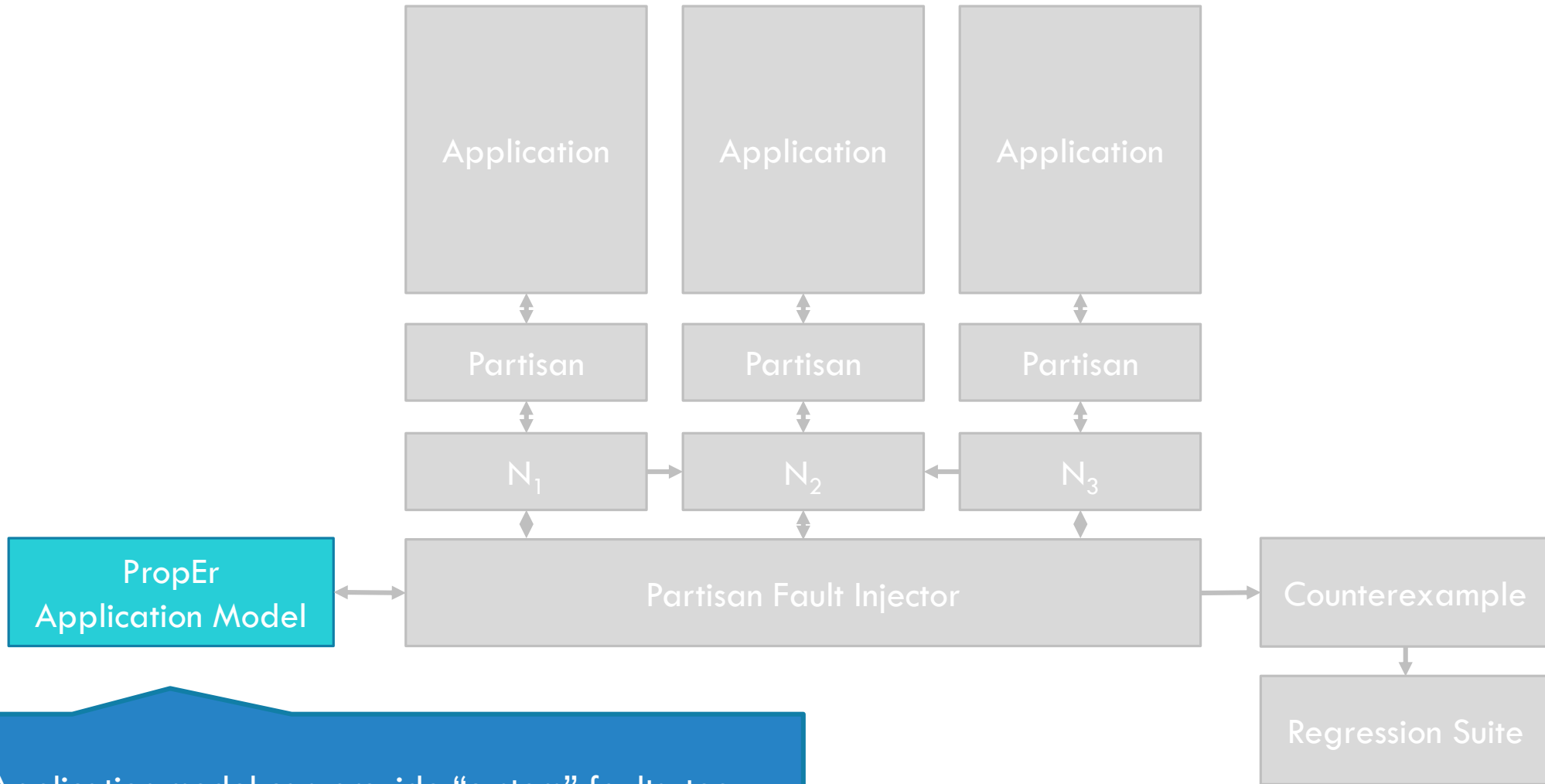
# VERIFYING RESILIENCE

Verifying your application runs correctly under failure.

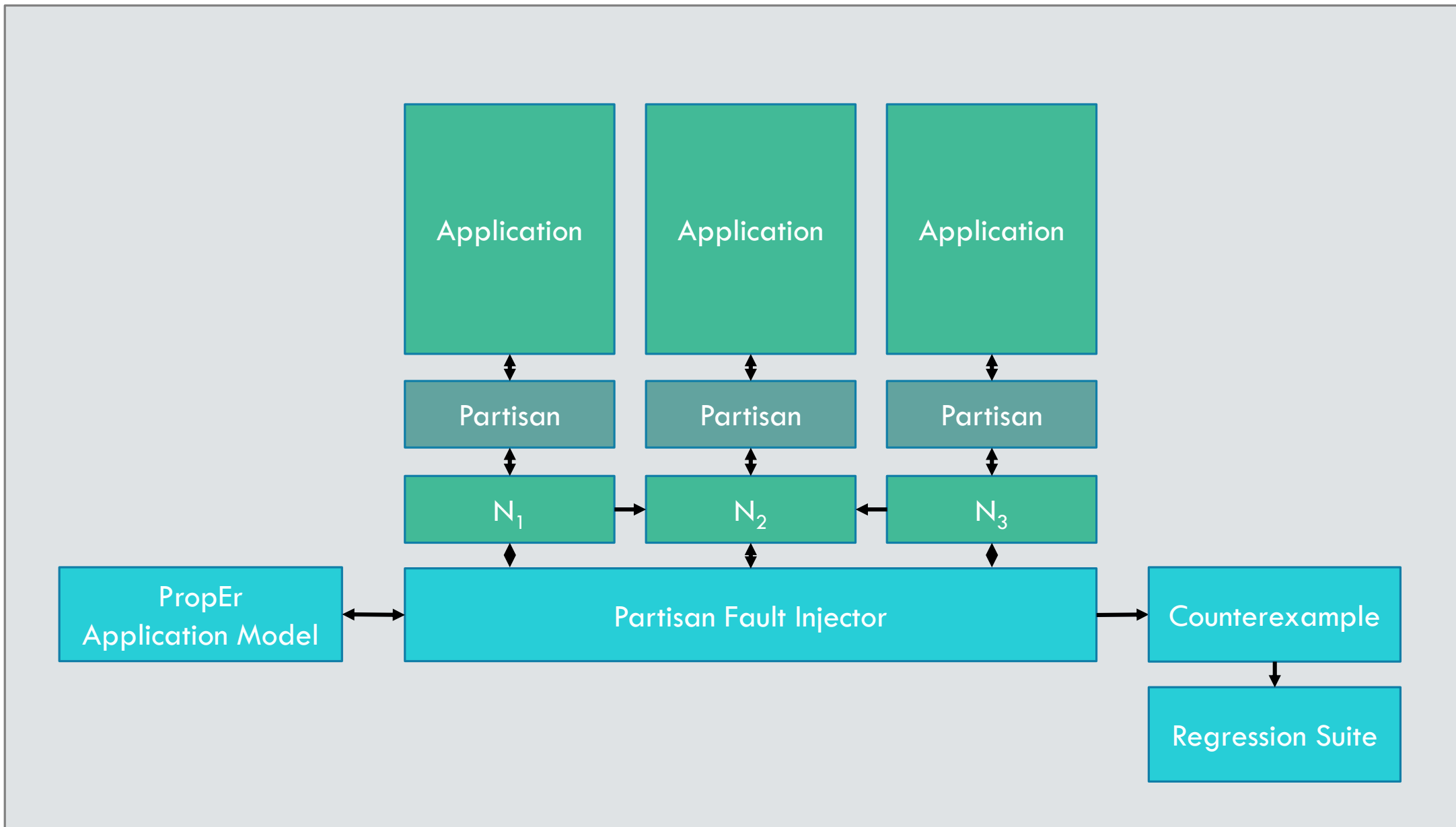






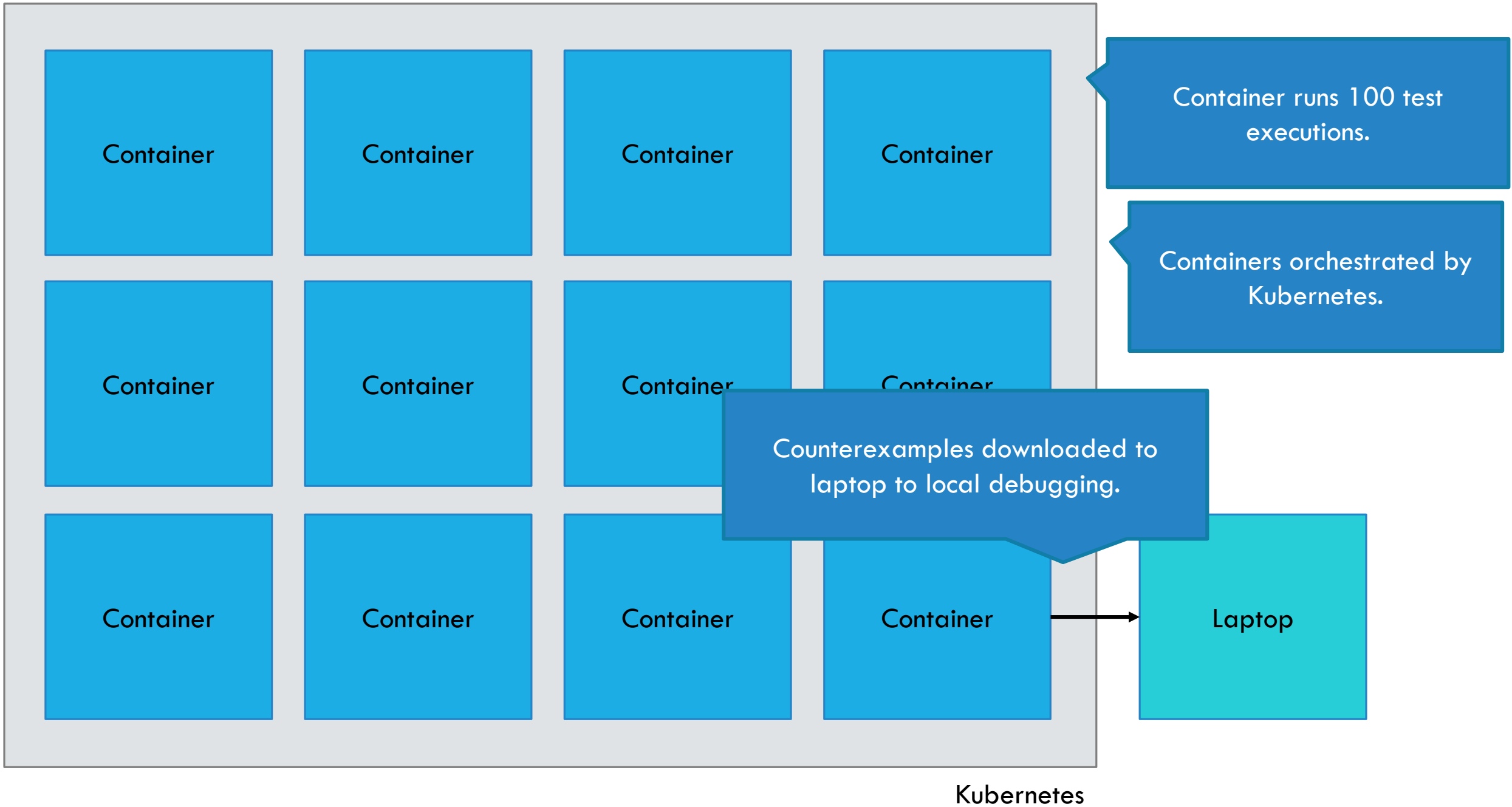


Application model can provide “custom” faults, too.  
e.g. Riak: disk loss, bit flips, etc.



Containerized Application





Container runs 100 test executions.

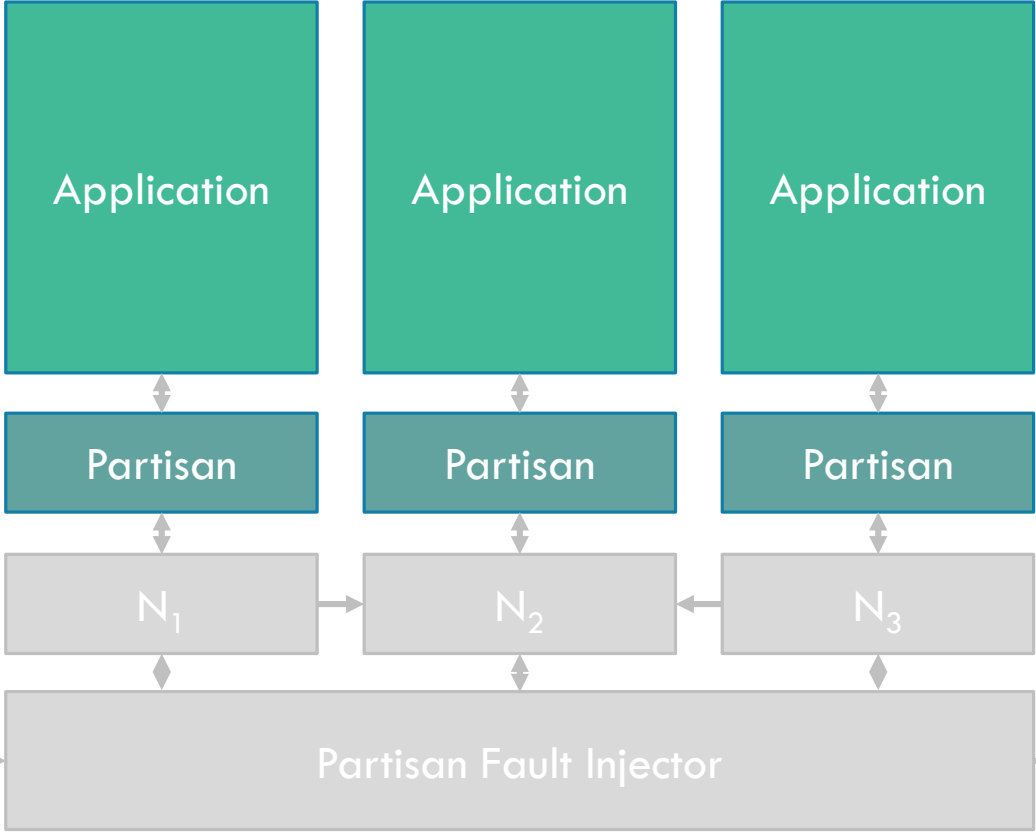
Containers orchestrated by Kubernetes.

Counterexamples downloaded to laptop to local debugging.

Laptop

Kubernetes

Ported Riak Core to Partisan, built a custom KV store.



Discovered several bugs in the key-value store under network partitions.

PropEr Application Model

Built a model to verify strong consistency, causal consistency, and eventual consistency.

Counterexample

Regression Suite

PropEr  
Application Model

Model contains incorrect assumption that all reads should return the value of the most recent successful write.

```
join n1 n2 : OK
join n1 n3 : OK
n1 write x 1 : OK
n1 read x 1 : OK
n1 read x 1 : OK
fault partition { n1 } { n2 n3 }
n1 read x 1 : TIMEOUT
```

Counterexample 1:  
Partition causes quorum unavailability.

```
join n1 n2 : OK
join n1 n3 : OK
fault egress_delay n2 n1
fault egress_delay n3 n1
n1 write x 1 : TIMEOUT
fault resolve_all
n1 read x 1 : 1
```

Counterexample 2:  
Unacknowledged write visible because of timeout.

```
join n1 n2 : OK
join n1 n3 : OK
n1 write x 1 : OK
fault byzantine n2 bitflip
n1 read x 1 : FAIL, {1, -1}
```

Counterexample 3:  
Parity bit flip error at node 2 returns disagreeing value.



Will random execution find all of the failures in my application?

2PC has only **one failure case**, manifesting itself in 3 schedules out of 4,096 possible schedules. (This considers possible omissions, not reorderings!)

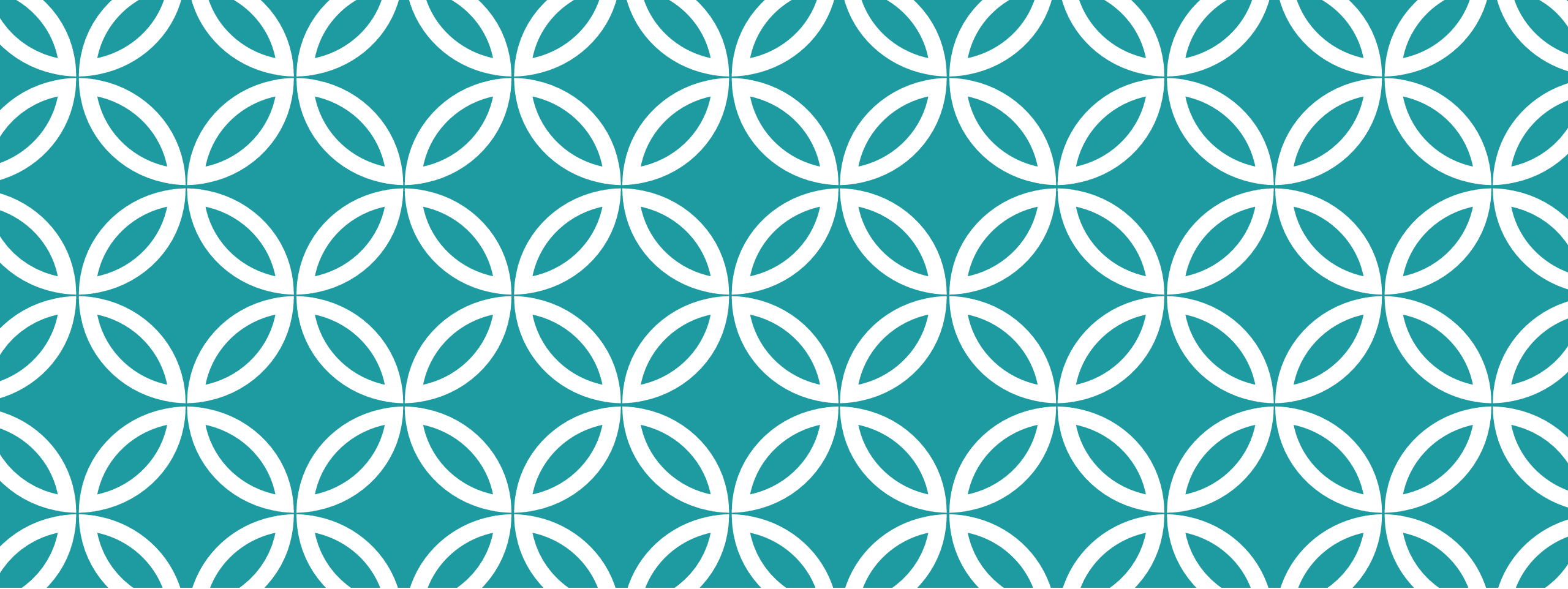
3PC has one failure case that appears in a few schedules. (From a total of 216,522 schedules, not considering reorderings.)



In short, no. To do that, we would need to search the entire execution space systematically.

But, we're working on this too!  
So, stay tuned!





# CONCLUSION

Bringing it all back home.

# CONCLUSION

Runtime system for improved scalability and reduced latency for distributed actors

- Prototype implementation with adoption in Erlang
- Uses techniques of parallelism, affinitized scheduling, and named channels
- Specialization of overlay network at runtime without change to semantics

Performance and Scalability

- Up to 34.9x improvement in throughput
- Up to 13.4x reduction in latency
- Order of magnitude in cluster size

Partisan v3

- Coming soon, new overlays, fault-injection, bugs fixes, and more!





Thanks for coming!

You can find me on twitter at [@cmeik!](#)

Have any questions?

Come and talk to me about  
**how I can help your company**  
with high performance distributed  
Erlang and fault-injection!



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